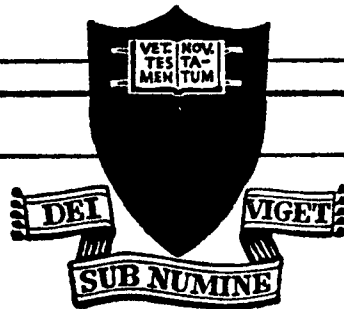
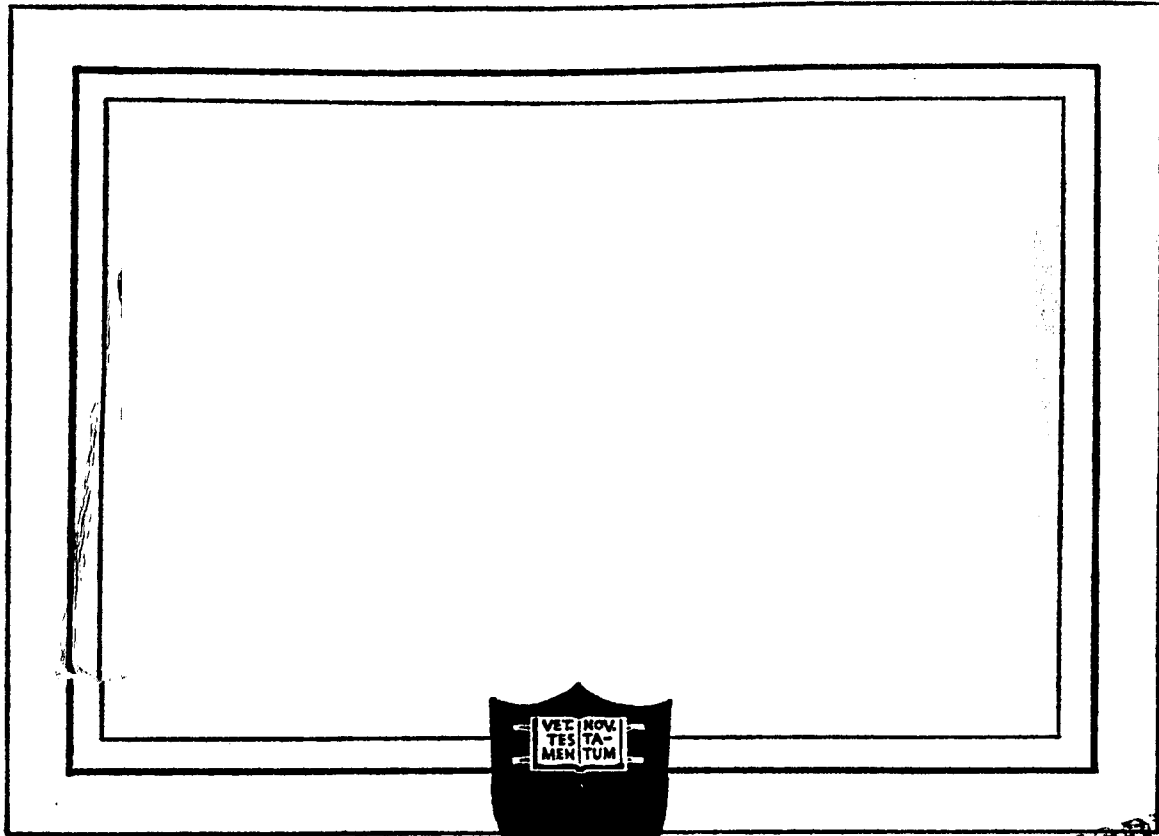


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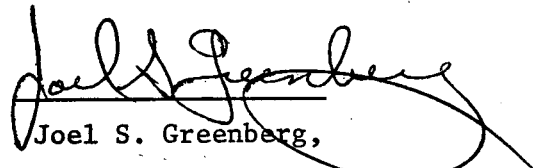
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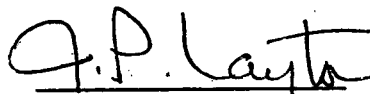
Reliability Model of a Monopropellant
Auxiliary Propulsion System

AMS Report No. 997

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THE AEROSPACE SYSTEMS LABORATORY
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ABSTRACT

A mathematical model and computer code have been developed to compute the reliability of a monopropellant blowdown spacecraft orbit adjustment propulsion system as a function of time. The reliability model interfaces with a computer code that models the performance of a blowdown (unregulated) monopropellant auxiliary propulsion system. The computer code acts as a performance model and as such gives an accurate time history of the system operating parameters. The basic timing and status information is passed on to and utilized by the reliability model which establishes the probability of successfully accomplishing each required orbit adjustment.

The mathematical model and computer code were developed as a background effort to verify the concepts prior to writing a reliability model based on the current NERVA propulsion system.

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RELIABILITY MODEL
OF A
MONOPROPELLANT AUXILIARY
PROPULSION SYSTEM

by Joel S. Greenberg

I. INTRODUCTION

A measure of how well a system performs or meets its design objectives is provided by the concept of system reliability. In general, reliability can be defined as the probability of successful system operation in the manner and under the conditions of intended use. Since space systems are normally designed to achieve multiple time dependent objectives, it is important to establish the reliability of achieving these objectives so that appropriate design trade-offs can be made. In order to demonstrate the importance of evaluating the reliability of multiple time dependent objectives and the basic techniques employed, a relatively simple mission was considered. Specifically, a mathematical model and associated computer code has been developed which computes the reliability of a monopropellant blowdown hydrazine spacecraft auxiliary propulsion system as a function of time. The propulsion system is used to adjust or modify the spacecraft orbit over an extended period of time. The multiple orbit corrections are the multiple objectives which the auxiliary propulsion system is designed to achieve. Thus the reliability model computes the probability of successfully accomplishing each of the desired orbit corrections. To accomplish this, the reliability model interfaces with a computer code that models the performance of a blowdown (unregulated) monopropellant auxiliary propulsion system. The computer code acts as a performance model and as such gives an accurate time history of the system operating parameters. The basic timing and status information is passed

on to and utilized by the reliability model which establishes the probability of successfully accomplishing the orbit corrections.

II. GENERAL PROPULSION SYSTEM DESCRIPTION

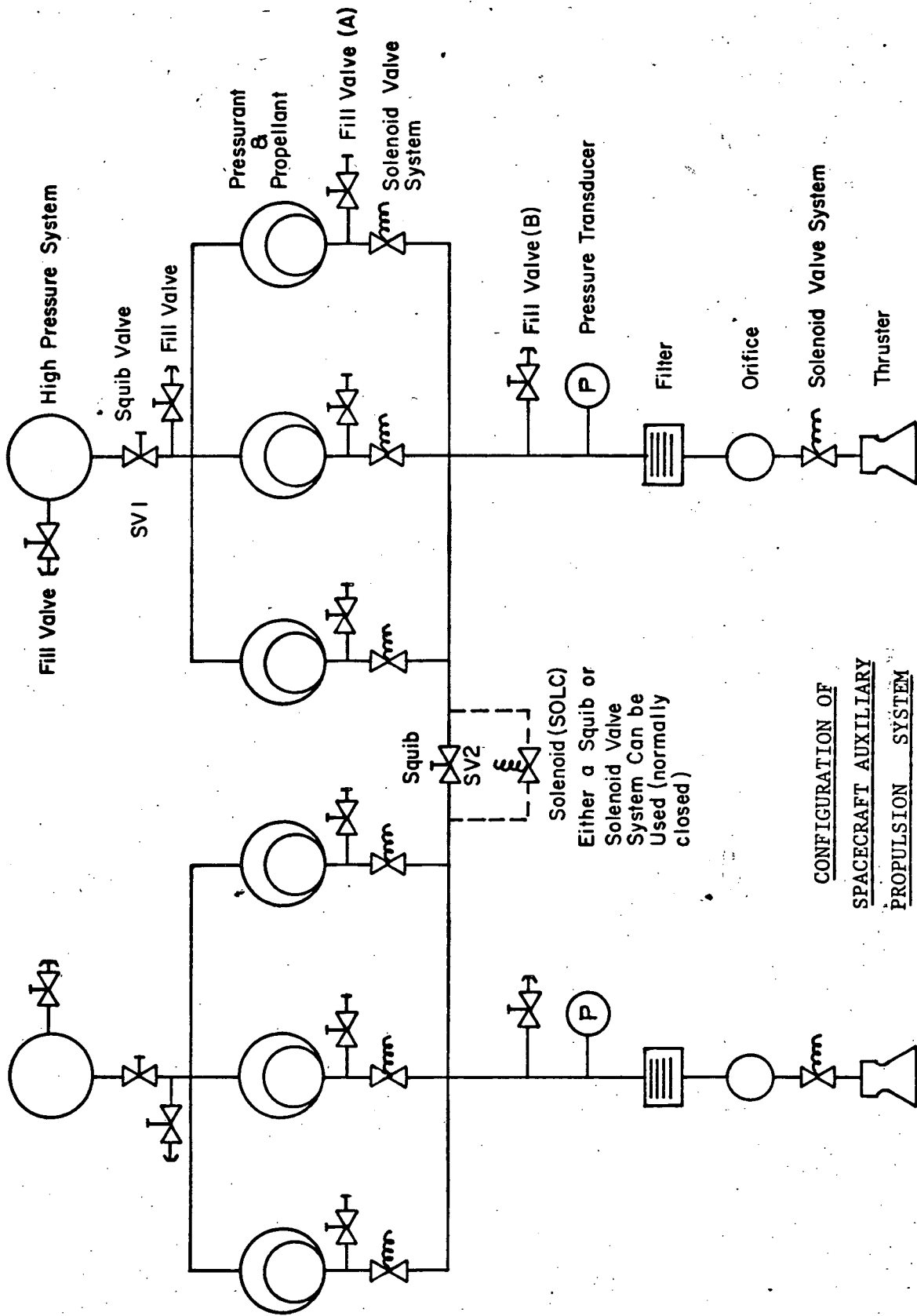
Monopropellant auxiliary propulsion systems are generally low thrust systems which are used for spacecraft attitude control and station keeping. Figure 1 illustrates the blowdown hydrazine propulsion system which has been modeled. The system consists of two identical monopropellant half-systems which are interconnected through a valve system such that the propellant from either half-system can be expended via either thruster. The half-system interconnecting valve system is normally in the closed position. The initial pressure in the propellant tank is such that the ullage gas will expand (blow-down) against the propellant, forcing it through the system during thrust periods until the propellant is depleted. The blow-down mode may be staged. That is, a pressurant tank may be placed in series with the main propellant tanks and at a predetermined propellant tank pressure the associated squib valve opens and the system is repressurized (i.e., blowdown occurs). Thus, sufficient pressure is maintained during normal operation to ensure that the desired amount of propellant can be expended.

The general propulsion system configuration which is modeled is as indicated in Figure 1. Within this configuration a number of alternatives are possible. These alternatives may be summarized as follows:

- (a) A single stage blow-down system may be considered. This implies the elimination of the high pressure system and its associated squib valve.

HALF-SYSTEM #2

HALF-SYSTEM #1



CONFIGURATION OF
SPACECRAFT AUXILIARY
PROPULSION SYSTEM

FIGURE 1

- (b) All squib valves are considered to consist of n valves in parallel.
- (c) The high pressure system can consist of m high pressure tanks in a parallel arrangement.
- (d) The half-system interconnecting valve system can consist of either squib or solenoid valves.
- (e) Either a single fill valve can be used for each pressurant and propellant tank or a single propellant fill valve can be used for each half-system.
- (f) Solenoid valve systems can consist of either a single valve, dual series valves, dual parallel valves, quad or quad connected valves.

III. PERFORMANCE MODEL*

The performance model⁽¹⁾ and associated computer code (the entire computer code for both the performance and reliability models is contained in Appendix I) yields an accurate time history of the propulsion system operating parameters. The mathematical equations used to represent the components are the basic orifice flow equation, thermodynamic expansion equation, and the various equations relating the rocket engine parameters. In order to run the performance program, the system hardware must be completely defined. The basic performance input data is summarized in Table I. Additional information describing thruster characteristic performance curves and specific

*The performance model was developed by Ralph Lake of RCA's Astro Electronic Division as part of course (E581- 1970/71) requirements at Princeton University.

TABLE IPERFORMANCE INPUT DATA

<u>Input Variable</u>	<u>Description</u>
VEJIN	Effective jet velocity (m/sec)
Z	Compressibility factor
CFIN	Nozzle thrust coefficient
DEN	Propellant density (kg/m^3)
AT	Nozzle thrust area (m^2)
PFIL	Initial tank pressure (n/m^2)
STG	Number of blowdown stages
CD	Orifice coefficient (all components)
A	Orifice area (all components)
P	Gas expansion exponent
DPT	Initial tank internal pressure drop (n/m^2)
PMO	Initial propellant mass (kg)
VTK	Tank volume (m^3)
VTINT	Volume of internal tank construction (m^3)
PW	Pulse width (sec)
WSC	Spacecraft mass (kg)
L	Number of maneuvers to be considered
ULV	High pressure ullage volume (m^3)
DELV	Velocity increment for each maneuver (m/sec)
PRES	Repressurization point pressure (n/m^2)
PCMIN	Minimum operating chamber pressure (n/m^2)
PCIN	Base point chamber pressure (n/m^2)
DP	System tubing diameter (m)

TABLE I

PERFORMANCE INPUT DATA

<u>Input Variable</u>	<u>Description</u>
TMAX	Temperature of propellant at input (°R)
TLNCH	Ambient propellant temperature at launch (°R)
RGAS	Gas constant
G	Gravitation constant
DT	Computation loop time increment (sec)

component parameters must also be provided (for example, effective jet velocity vs. chamber pressure, nozzle thrust coefficient vs. chamber pressure).

The performance model deals with the flow restrictors (valves, orifice, filters) and sizes the trim orifice to achieve the desired base point parameters for beginning of life operation. For a given mission, the velocity increment schedule, the thruster pulse width and number of blowdown stages are the primary inputs. Efficiency factors for the thruster depend on both operating pressure and the pulse width. These factors are introduced during an iteration process in terms of the effective jet velocity versus chamber pressure and thruster efficiency versus pulse number.* The model iterates the pulsing performance until the required velocity increment for that (Kth) maneuver is reached. The model keeps track of the number of impulses required to accomplish the maneuver.

The model iterates the gas expansion process with time (in terms of the blowdown conditions) to determine the propellant flow rate and calculates tank pressure, chamber pressure, propellant remaining, effective jet velocity, specific impulse, thrust, mass flow rate, total impulse, and burn time. When the propellant mass decreases to zero the iteration terminates. The program may also be terminated if the system goes below the minimum operating chamber pressure. All of the above parameters are printed out for each of the maneuvers.

*All curves are input in table form and a subroutine (STINT) is utilized to interpolate and return the correct values to the main program.

The output (see Appendix II) lists the important system operating parameters as a function of the maneuver. This allows the propulsion system performance to be monitored as a function of time and indicates whether or not the modeled system fulfills the mission requirements.

IV. RELIABILITY MODEL (2-7)

General

The term reliability, as used herein, denotes the probability that a component, subsystem, or system (as the case may be) will perform its intended functions adequately under defined operating conditions at a designated time for a specified operating period. Reliability predicts mathematically the equipments behavior under expected operating conditions. Reliability is synonymous with probability of survival or probability of success.

The starting point of reliability analysis is the determination or specification of the intended functions and successful operation or adequate performance (i.e., the definition of success). To judge adequate performance involves the observation of inadequate performance in operation; therefore, the observation of malfunctions and failures which violate the requirement for an "adequate performance." The frequency of failures and malfunctions is an important parameter used in the mathematical formulation of reliability. This parameter is referred to as the failure rate. It is usually measured in terms of the number of failures per unit time or cycle of operation.

The reliability model considers both random or chance failures and wear-out failures. Random or chance failures are characterized by a failure rate which is independent of time (i.e., a constant). Under this condition the

probability distribution of time to failure is given by

$$f(t) = \lambda \exp (-\lambda t)$$

where the failure rate λ may be statistically estimated by experiment.

Reliability, that is the probability that the device is functioning properly at time t , is given by

$$R(t) = 1 - \int_0^t f(t) dt = \exp (-\lambda t)$$

where λ is the constant chance failure rate and t is the operating time for which it is desired to determine the reliability, $R(t)$. The exponential distribution is independent of device age. When the number of operating cycles is more meaningful than time, the reliability equation can be written as

$$R(c) = \exp (-\lambda t)$$

where $R(c)$ is the reliability at c operating cycles, or the probability of survival through c cycles.

The normal density function is used to characterize wearout failures and is of the form

$$f(T) = \frac{1}{\sqrt{2\pi}\sigma} \exp \left[-\frac{(T - M)^2}{2\sigma^2} \right]$$

where T is the component or device age, M is the expected or mean life, and σ is the standard deviation of the lifetimes. The reliability or probability of survival to time T is thus given by

$$R(T) = 1 - \int_0^T f(t) dt = \frac{1}{\sqrt{2\pi}\sigma} \int_t^{\infty} \exp \left[-\frac{(t - M)^2}{2\sigma^2} \right] dt$$

Since chance and wearout phenomena usually occur simultaneously, it is necessary to evaluate their combined effects. Thus it is desired to evaluate

the reliability of a mission having a duration of t hours and employing a component that has an age of T hours at the beginning of the mission. The combined probability of failure in t equals the probability of failing of chance and /or wearout in the interval t , at the age of T . Therefore,

$$Q(t) = Q_c(t) + F_w(t) - Q_c(t) \cdot F_w(t)$$

where $Q(t)$ is the probability of failing at time t , $Q_c(t)$ is the probability of failing at time t due to chance failures, and $F_w(t)$ is the probability of failing at time t due to wearout. $F_w(t)$ is the a posteriori or conditional probability of a failure given survival to an age T . Therefore, it can be shown⁽²⁾ that the probability of successful operation is given by

$$R(t) = e^{-\lambda t} \frac{\int_{T+t}^{\infty} e^{-(T-M)^2/2\sigma^2} dT}{\int_T^{\infty} e^{-(T-M)^2/2\sigma^2} dT}$$

A similar expression can be written in terms of cycles of operation.

System reliability is normally a calculated or computed quantity. It is based upon consideration of the components used in the system, how they are used, their modes of failure, and their probability of successful operation. Component reliabilities are normally obtained from tests which yield information about failure rates. System reliability is thus an extrapolation of the component reliabilities using a mathematical model to describe the system operation.

From basic probability theory it can be seen that the probability of successful operation of n components connected in series is

$$R_s(t) = R_1(t) \cdot R_2(t) \cdots R_n(t) = \exp \left(- \sum_{i=1}^n \lambda_i t \right)$$

This is called the "product law of reliabilities" for components operating in a serial arrangement. A similar equation can be developed for components operating

in parallel (i.e., in order to have a system failure all parallel components must fail). Therefore the probability of no failures is

$$Q_p(t) = Q_1(t) \cdot Q_2(t) \cdot \dots \cdot Q_n(t) = \prod_{i=1}^n Q_i(t)$$

where $Q_i(t)$ = probability of no failure = $1 - R_i(t)$. This is termed the "product law of unreliabilities in parallel operation." This can also be written as

$$R_p(t) = 1 - \prod_{i=1}^n [1 - R_i(t)]$$

where $R_p(t)$ represents the probability of successful operation (i.e., at least one of the components operating satisfactorily).

These are thus the basic reliability concepts which are utilized in the reliability model described in the following section.

Mathematical Model

The mathematical model to be described in detail computes the reliability of the monopropellant blowdown spacecraft auxiliary propulsion system illustrated in Figure 1. The model establishes the probability of performing each of a series of orbit corrections. The model is based upon the following assumptions:

- a. The propulsion system consists of two symmetric half-systems which are interconnected through a valve system (normally closed). The interconnecting valve system is opened when one of the components in the thruster system (fill valve, pressure transducer, lines, filter, orifice, valve system, thruster) in use fails.
- b. The valve systems which control the propellant flow (in series with the propellant tanks) are normally closed and must therefore open to allow propellant flow.
- c. Each half-system contains three propellant tanks with associated valve systems. All three valves are normally closed and are opened

simultaneously to allow propellant flow. Therefore, when there is no failure, propellant is drawn in equal amounts from the three propellant tanks.

- d. The useable propellant of a single half-system is expended before the second half-system is utilized. This implies that repressurization of a single half-system is performed prior to using the second half-system.
- e. If a leak develops in the pressurant system, the associated half-system propellant system fails.

Definitions of all input variables (for the reliability model) are given in Table II.

As discussed previously, the reliability model is designed to interface with the performance model. This imposes several constraints upon the reliability model. The performance model is implemented such that the performance of each half-system is evaluated independently. Thus the performance model must be cycled through twice - once for each half-system. When the first half-system is being evaluated $HALFZ = 1$ and when the second half-system is being evaluated $HALFZ = 2$.

Since the total propellant mass is distributed equally between the two half-systems,

$$PMO = PMO/2$$

When $HALFZ = 1$

Then $WSC = \text{as input}$

$$PM1_k = PM_k$$

$$PM2_k = PMO$$

TABLE II

RELIABILITY MODEL - INPUT DATA

<u>Term</u>	<u>Dimension</u>	<u>Max. Value</u>	<u>Definition</u>
TIMEZ (K)	1 $\phi\phi$	XXXX.XX	Time (days) of occurrence of K orbit correction.
NBZ	1	XX	Average number of brazed joints per thruster engine assembly.
NPZ	1	XX	Two symmetric half-systems are considered with each half system consisting of three propellant tank groups. NPZ represents the number of propellant tanks per group.
NS1Z	1	XX	Number of parallel squib valves in high pressure system.
NS2Z	1	XX	Number of parallel squib valves in half-system connecting valve system. When CONVZ=SOL then set NS2Z=0.
NSCZ	1	XX	Number of catalyst screens per thruster.
NTZ	1	XX	Number of high pressure tanks per half-system.
NWHPZ	1	XXX	Number of weld connections (per half-system) between the high pressure squib valve and the pressurant and propellant tanks.
NWPZ	1	XXX	Number of weld connections (per propellant tank sys.) between propellant tank and propellant tank solenoid valve system.
NWTZ	1	XXX	Number of weld connections (per half-system) between propellant tank solenoid valve systems and thruster.

TABLE II

RELIABILITY MODEL - INPUT DATA (contd)

<u>Term</u>	<u>Dimension</u>	<u>Max. Value</u>	<u>Definition</u>
VSC	1	"S", "DS", "DP", "Q", "QC"	Specification of type of valve system configuration to be used for the half-system connecting solenoid valve system. Only required when CONVZ="SOL".
VSP	1	"S", "DS", "DP", "Q", "QC"	Specification of type valve system configuration to be used for the propellant solenoid valve system.
VST	1	"S", "DS", "DP", "Q", "QC"	Specification of type of valve system configuration to be used for the thruster solenoid valve system.
CONVZ	1	"SQ" or "SOL"	Specification of the type of valve to be used for connecting the two half-systems. "SQ" refers to squib and "SOL" refers to solenoid.
SPFVZ	1	"Y" or "N"	When SPFVZ = Y, a single propellant fill valve will be used for each half-system. When SPFVZ=N, a single propellant fill valve will be used for each propellant tank.
MBZ	1	XXX	Average or mean number of cycles for bladder failure rate due to wear out phenomena.
STDZ	1	XXX	Standard deviation (cycles) of bladder wear out failures.
PFSZ	1	.XXXXXX	Probability of a squib firing successfully when required.
LCZ	1	XXX.XXXX	Random or chance failure rate of valve caps (failures/10 ⁶ hours).

TABLE IIRELIABILITY MODEL - INPUT DATA (contd)

<u>Term</u>	<u>Dimension</u>	<u>Max. Value</u>	<u>Definition</u>
LCLZ	1	XXX.XXXX	Random or chance failure rate of solenoid valve for failing in a closed position (failure/ 10^6 cycles).
LOPZ	1	XXX.XXXX	Random or chance failure rate of solenoid valve for failing in an open position (failures/ 10^6 cycles).
LVSZ	1	XXX.XXXX	Random or chance failure rate of solenoid valve for excessive leakage past the valve seat (failures/ 10^6 hours).
LVZ	1	XXX.XXXX	Random or chance failure rate of fill valves (quick disconnect) (failures/ 10^6 hours).
LWZ	1	XXX.XXXX	Random or chance failure rate of welded connections (failures/ 10^6 hours).
LPZ	1	XXX.XXXX	Random or chance failure rate of pressure transducer (failure/ 10^6 hours).
LFZ	1	XXX.XXXX	Random or chance failure rate of filter media (failure/ 10^6 hours).
LBRZ	1	XXX.XXXX	Random or chance failure rate of brazed joints (failures/ 10^6 hours).
LSCZ	1	XXX.XXXX	Random or chance failure rate of catalyst envelope screens (failures/ 10^6 hours).
LBZ	1	XXX.XXXX	Random or chance failure rate of bladder (failures/ 10^6 hours).

When HALFZ = 2

Then $WSC = WSC + PM1_k$

Where $PM1_0 = PMO$

$PM1_k = PM1_{k-1}$

Prior to output, set $PM_k = PM1_k + PM2_k$

WSC is the mass of the spacecraft, PM_k is the propellant remaining at the completion of the Kth orbit correction in the half-system under consideration, and $PM1_k$ and $PM2_k$ represent the propellant in the first and second half-systems, respectively. It should be noted that when HALFZ = 2, the spacecraft mass must be initialized to take into account propellant remaining in the first half-system.

A schedule of velocity increments for each orbit correction is a necessary input for the performance computations. Similarly, the time ($TIMEZ_k$) of each of the K orbit corrections is a necessary input for the reliability computations. Since the input data is specified in days and the computations are performed in terms of hours,

$$TIMEZ_k = 24 \cdot TIMEZ_k$$

The performance model keeps track of which half-system is in use. The determination of the half-system in use is based upon the assumption that a half-system will be used until all usable propellant is expended. This includes the repressurization cycle. Therefore,

When first half-system is in use

Then HALFZ = 1

When second half-system is in use

Then HALFZ = 2

It is necessary, as will be seen in the following pages, to have knowledge as to when repressurization takes place. To achieve this the variable

MODE is defined. MODE is equal to zero prior to repressurization and equal to 2 after repressurization. MODE1 and MODE2 refer to the repressurization status of half-systems 1 and 2 respectively. The value of MODE is available from the performance portion of the model. Thus,

When HALFZ = 1 and MODE = 0

Then MODE1 = 0 and MODE2 = 0

When HALFZ = 1 and MODE = 2

Then MODE1 = 2 and MODE2 = 0

When HALFZ = 2 and MODE = 0

Then MODE1 = 2 and MODE2 = 0

When HALFZ = 2 and MODE = 2

Then MODE1 = 2 and MODE2 = 2

It is assumed that all fill valves used in the system are capped and are of the quick disconnect type. In order to have a failure both the fill valve and the cap must fail. Therefore, the reliability of the fill valves, $RFVZ_k$, at the completion of the K^{th} orbit correction is

$$RFVZ_k = 1.0 - [1.0 - \exp(-LVZ \cdot TIMEZ_k \cdot 10^{-6})] \cdot [1.0 - \exp(-LCZ \cdot TIMEZ_k \cdot 10^{-6})]$$

where LVZ and LCZ are the chance failure rates of fill valves and valve caps (failures per 10^6 hours), respectively.

The reliability of the high pressure tank system, RTZ_k , is given by

$$RTZ_k = \exp[-NTZ \cdot LWZ \cdot TIMEZ_k \cdot 10^{-6}]$$

where it is assumed that the failure mode is due to leakage through the weld joints. NTZ and LWZ are the number of parallel high pressure tanks

per half-system and the random or chance failure rate of welded connections (failures per 10^6 hours), respectively. Similarly the reliability of the propellant tank weld ring is

$$RPTZ_k = \exp \left[-LWZ \cdot TIMEZ_k \cdot 10^{-6} \right]$$

The reliability of the squib valve system (SV1) attached to the high pressure tanks is given by

$$RSV1Z = 1.0 - (1.0 - PFSZ)^{NS1Z}$$

where PFSZ is the probability of a squib firing successfully when required and NS1Z is the number of squibs in parallel.

There are a number of connections in the system which consist of weld (or brazed) joints. The welded connections have been broken down into three groups namely (a) those between the squib valve (SV1) and the pressurant and propellant tanks, (b) those between the propellant tank and the associated solenoid valve system, and (c) those between the propellant tank solenoid valve system and the thruster. The reliability of these three groups of connections are

$$RLHPZ_k = \exp \left[-NWHZ \cdot LWZ \cdot TIMEZ_k \cdot 10^{-6} \right]$$

$$RLPPZ_k = \exp \left[-NWPZ \cdot LWZ \cdot TIMEZ_k \cdot 10^{-6} \right]$$

$$RLTZ_k = \exp \left[-NWTZ \cdot LWZ \cdot TIMEZ_k \cdot 10^{-6} \right]$$

where NWHZ, NWPZ, NWTZ are the number of connections in each of the above three groups, respectively.

The reliability of the half-system connecting valve system depends upon whether squib or solenoid valves are used. When squib valves are used, i.e.,

When CONVZ = "SQ" (or not "SOL")

Then

$$RSV2Z_k = 1.0 - (1.0 - PFZ)^{NS2Z}$$

where NS2Z is the number of squib valves in parallel and CONVZ is the input variable which specifies whether a squib (SQ) or a solenoid (SOL) system is to be used.

The reliability of solenoid valves depends upon both time and the number of cycles of operation. The solenoid valve system used for the half-system valve requires only one cycle of operation, i.e., it is normally closed and is required to open only when the thruster system in use fails. The failure modes of a solenoid valve are failure to open when required, failure to close when required, and excessive leakage past the valve seat. It is assumed that leakage past the valve seat is time dependent and the other two failure modes are cycle dependent.

The probability of a single solenoid valve not failing closed in a single cycle of operation, RCSZ, is given by

$$RCSZ = \exp [-LCLZ \cdot 10^{-6}]$$

and the probability of no open failure or leak past the valve seat in a single cycle of operation, ROSZ_k, is given by

$$ROSZ_k = \exp [-LOPZ \cdot 10^{-6} - LVSZ \cdot TIMEZ_k \cdot 10^{-6}]$$

LCLZ and LOPZ are the random or chance failure rates (failures per 10⁶ cycles) of a solenoid valve failing in a closed and open position, respectively. LVSZ is the failure rate (failures per 10⁶ hours) of a solenoid valve due to excessive leakage past the valve seat.

The solenoid valves may be arranged in a number of different configurations. A number of configurations are considered by the reliability model; namely the single valve ("S"), dual series ("DS"), dual parallel ("DP"), quad system ("Q"), and quad connected ("QC") systems. These configurations are

illustrated in Appendix III where reliability equations are derived in terms of the basic single valve reliability equations. Therefore, the reliability of the valve system is given by

When VSC = "S"

Then

$$RSOLCZ_k = ROSZ_k + RCSZ - 1.0$$

When VSC = "DS"

Then

$$RSOLCZ_k = RCSZ^2 - [1.0 - ROSZ_k]^2$$

When VSC = "DP"

Then

$$RSOLCZ_k = ROSZ_k^2 - [1.0 - RCSZ]^2$$

When VSC = "Q"

Then

$$RSOLCZ_k = [1.0 - (1.0 - ROSZ_k^2)]^2 - [1.0 - RCSZ^2]^2$$

When VSC = "QC"

Then

$$RSOLCZ_k = [1.0 - (1.0 - RCSZ)^2]^2 - [1.0 - ROSZ_k^2]^2$$

where VSC is the input variable which specifies the particular solenoid valve configuration to be used. It should be noted that RCSZ is not subscripted since only one cycle of operation is required.

The reliability of the pressure transducer is assumed to depend primarily upon the time of actual use. The time of actual use, TIM_k , is

the thrust time* and is computed by the performance portion of the model.

Thus, the reliability of the pressure transducer is given by

When HALFZ = 1

Then

$$RPD1Z_k = \exp \left[-LPZ \cdot \frac{TIM_k}{3600} \cdot 10^{-6} \right]$$

$$RPD2Z_k = 1.0$$

When HALFZ = 2

Then

$$RPD1Z_k = RPD1Z_{k-1} \quad \text{where } RPD1Z_0 = 1.0$$

$$RPD2Z_k = \exp \left[-LPZ \cdot \frac{TIM_k}{3600} \cdot 10^{-6} \right]$$

where LPZ is the random or chance failure rate (failure/ 10^6 hours) of the pressure transducer. RPD1Z_k and RPD2Z_k are the reliabilities of the pressure transducers in half-systems 1 and 2, respectively.

It is assumed that the reliability of the filter assembly, RF1Z_k and RF2Z_k for half-systems 1 and 2, respectively, are a function of both absolute time and use time. Absolute time must be considered because of the possibility of failure of a welded connection. Therefore, the reliability of the filter assemblies is given by

*Since the performance model considers each half-system separately, TIM_k is the thrust time associated with the half-system being evaluated. TIM_k is initialized to zero after completion of the performance evaluation of the first half-system.

When HALFZ = 1

Then

$$RF1TZ_k = \exp \left[-LFZ \cdot \frac{TIM_k}{3600} \cdot 10^{-6} \right]$$

$$RF1Z_k = RF1TZ_k \cdot \exp \left[-LWZ \cdot TIMEZ_k \cdot 10^{-6} \right]$$

$$RF2Z_k = \exp \left[-LWZ \cdot TIMEZ_k \cdot 10^{-6} \right]$$

When HALFZ = 2

Then

$$RF1TZ_k = RF1TZ_{k-1} \quad \text{where } RF1TZ_0 = 1.0$$

$$RF1Z_k = RF1TZ_k \cdot \exp \left[-LWZ \cdot TIMEZ_k \cdot 10^{-6} \right]$$

$$RF2Z_k = \exp \left[-LFZ \cdot \frac{TIM_k}{3600} \cdot 10^{-6} - LWZ \cdot TIMEZ_k \cdot 10^{-6} \right]$$

where LFZ is the chance failure rate (failures/ 10^6 hours) of the filter media.

The performance portion of the model computes the number of impulses or cycles (J_k) required to achieve the velocity increment of the k^{th} orbit correction. The total number of cycles of operation of half-systems 1 and 2 ($CYCL1Z_k$ and $CYCL2Z_k$, respectively) are thus given by

When HALFZ = 1

When $k = 1$

$$\text{Then } CYCL1Z_k = J_k$$

$$CYCL2Z_k = 0$$

When $k > 1$

$$\text{Then } CYCL1Z_k = CYCL1Z_{k-1} + J_k$$

$$CYCL2Z_k = 0$$

When HALFZ = 2

When $k = 1$

$$\text{Then } CYCL1Z_k = 0$$

$$CYCL2Z_k = J_k$$

When $k > 1$

Then $CYCL1Z_k = CYCL1Z_{k-1}$

$$CYCL2Z_k = CYCL2Z_{k-1} + J_k$$

The reliability equations for the thruster solenoid valve systems are similar to the half-system connecting valve. The single exception is that the thruster solenoid valves will experience many cycles of operation. The probability of no closed failure of a single valve is

$$RC1Z_k = \exp [-LCLZ \cdot CYCL1Z_k \cdot 10^{-6}]$$

$$RC2Z_k = \exp [-LCLZ \cdot CYCL2Z_k \cdot 10^{-6}]$$

and the probability of no open failure or leak past the valve seat (of a single valve) is

$$RO1Z_k = \exp [-LOPZ \cdot CYCL1Z_k \cdot 10^{-6} - LVSZ \cdot TIMEZ_k \cdot 10^{-6}]$$

$$RO2Z_k = \exp [-LOPZ \cdot CYCL2Z_k \cdot 10^{-6} - LVSZ \cdot TIMEZ_k \cdot 10^{-6}]$$

where RC1Z AND RO1Z refer to the first half-system and RC2Z and RO2Z refer to the second half-system. As before, several different valve system types are allowed. These are specified by VST. The valve system reliability is given by RST1Z for the first half-system and RST2Z for the second half-system. Therefore (refer to Appendix III),

When $VST = "S"$

Then

$$RST1Z_k = RO1Z_k + RC1Z_k - 1.0$$

$$RST2Z_k = RO2Z_k + RC2Z_k - 1.0$$

When $VST = "DS"$

Then

$$RST1Z_k = RC1Z_k^2 - [1.0 - RO1Z_k]^2$$

$$RST2Z_k = RC2Z_k^2 - [1.0 - RO2Z_k]^2$$

When VST = "DP"

Then

$$RST1Z_k = R01Z_k^2 - [1.0 - RC1Z_k]^2$$

$$RST2Z_k = R02Z_k^2 - [1.0 - RC2Z_k]^2$$

When VST = "Q"

Then

$$RST1Z_k = [1.0 - (1.0 - R01Z_k)^2]^2 - [1.0 - RC1Z_k^2]^2$$

$$RST2Z_k = [1.0 - (1.0 - R02Z_k)^2]^2 - [1.0 - RC2Z_k^2]^2$$

When VST = "QC"

Then

$$RST1Z_k = [1.0 - (1.0 - RC1Z_k)^2]^2 - [1.0 - R01Z_k^2]^2$$

$$RST2Z_k = [1.0 - (1.0 - RC2Z_k)^2]^2 - [1.0 - R02Z_k^2]^2$$

In a similar manner, the reliability of the pressurant and propellant tank solenoid valve system can be established.

When VSP = "S"

Then

$$RSP1Z_k = R01Z_k + RC1Z_k - 1.0$$

$$RSP2Z_k = R02Z_k + RC2Z_k - 1.0$$

When VSP = "DS"

Then

$$RSP1Z_k = RC1Z_k^2 - [1.0 - R01Z_k]^2$$

$$RSP2Z_k = RC2Z_k^2 - [1.0 - R02Z_k]^2$$

When VSP = "DP"

Then

$$RSP1Z_k = R01Z_k^2 - [1.0 - RC1Z_k]^2$$

$$RSP2Z_k = R02Z_k^2 - [1.0 - RC2Z_k]^2$$

When VSP = "Q"

Then

$$RSP1Z_k = [1.0 - (1.0 - R01Z_k)^2]^2 - [1.0 - RC1Z_k]^2$$

$$RSP2Z_k = [1.0 - (1.0 - R02Z_k)^2]^2 - [1.0 - RC2Z_k]^2$$

When VSP = "QC"

Then

$$RSP1Z_k = [1.0 - (1.0 - RC1Z_k)^2]^2 - [1.0 - R01Z_k]^2$$

$$RSP2Z_k = [1.0 - (1.0 - RC2Z_k)^2]^2 - [1.0 - R02Z_k]^2$$

In the above equations, $RSP1Z_k$ refers to the first half-system and $RSP2Z_k$ refers to the second half-system and VSP is the input variable which specifies the type of valve configuration to be considered.

The thrusters contain a number of catalyst screens with failure rate LSCZ. The reliability of the catalyst screens is a function of usage time. The thruster also contains a number of brazed joints (failure rate given by LBRZ) and weld joints. The reliability of the two thrusters is given by $RTH1Z_k$ and $RTH2Z_k$. Therefore,

When HALFZ = 1

Then

$$RTHZ_k = \exp[-NSCZ \cdot LSCZ \cdot \frac{TIM_k}{3600} \cdot 10^{-6}]$$

$$RTH1Z_k = RTHZ_k \cdot \exp [(-NBZ \cdot LBRZ \cdot TIMEZ_k - 2 \cdot LWZ \cdot TIMEZ_k) \cdot 10^{-6}]$$

$$RTH2Z_k = \exp [(-NBZ \cdot LBRZ \cdot TIMEZ_k - 2 \cdot LWZ \cdot TIMEZ_k) \cdot 10^{-6}]$$

When HALFZ = 2

Then

$$RTHZ_k = RTHZ_{k-1} \quad \text{where } RTHZ_0 = 1.0$$

$$RTH1Z_k = RTHZ_k \cdot \exp [(-NBZ \cdot LBRZ \cdot TIMEZ_k - 2 \cdot LWZ \cdot TIMEZ_k) \cdot 10^{-6}]$$

$$RTH2Z_k = \exp [(-NBZ \cdot LBRZ \cdot TIMEZ_k - 2 \cdot LWZ \cdot TIMEZ_k - NSCZ \cdot \frac{TIM_k}{3600} \cdot 10^{-6})]$$

The last component to be considered is the pressurant and propellant tank bladder. The function of the bladder is to separate the pressurant and the propellant. The bladder can fail due to the random or chance failure rate, LBZ, of holes developing in the bladder. The bladder is also subject to wearout phenomena since the bladder is forced to contract and expand for several cycles of operation. Prior to the need for repressurization of the first half-system, that is

When MODE1 < 2

Then

$$RB1Z_k = \exp [-NPZ \cdot LBZ \cdot TIMEZ_k \cdot 10^{-6}]$$

$$RB2Z_k = RB1Z_k$$

When repressurization of the first half-system is required, the reliability equations become

When MODE1 = 2 and MODE2 < 2

Then

$$RB1Z_k = \left\{ \exp [-NPZ \cdot LBZ \cdot TIMEZ_k \cdot 10^{-6}] \right\} \\ \cdot \left\{ \frac{\int_0^{\infty} [\exp(-(AZ - MBZ)^2 / (2.0 \cdot STDZ^2))] \cdot dAZ}{\int_0^{\infty} [\exp(-(AZ - MBZ)^2 / (2.0 \cdot STDZ^2))] \cdot dAZ} \right\} \\ RB2Z_k = \exp [-NPZ \cdot LBZ \cdot TIMEZ_k \cdot 10^{-6}]$$

where the ratio of the integrals indicates the probability of a second successful contract/expand cycle given that it survived the first. The first cycle is due to the initial filling of the tanks. When repressurization is required of the second half-system, the reliability equations are given by

When MODE1 = 2 and MODE2 = 2

Then

$$RB1Z_k = \left\{ \exp [-NPZ \cdot LBZ \cdot TIMEZ_k \cdot 10^{-6}] \right\} \cdot \left\{ 2 \int_{-\infty}^{\infty} [\exp (-(AZ - MBZ)^2 / (2.0 \cdot STDZ^2))] \cdot dAZ \right\} / \left\{ 1 \int_{-\infty}^{\infty} [\exp (-(AZ - MBZ)^2 / (2.0 \cdot STDZ^2))] \cdot dAZ \right\}$$

$$RB2Z_k = RB1Z_k$$

In the above equations it is assumed that wearout phenomena are adequately characterized by the normal distribution where MBZ is the expected number of cycles and STDZ is the standard deviation of the number of cycles to failure.

Before getting into the general system reliability equations, two configuration decisions must be made. A decision (SPFVZ) must be made as to whether the configuration will contain a single propellant fill valve for each half-system or a single valve per propellant tank. A decision (CONVZ) must also be made as to the type of valve system to be used for the half-system connecting valve. Therefore,

When SPFVZ = "Y"

(i.e., a single propellant fill valve is to be used for each half-system)

Then

$$RFV1Z_k = 1.0$$

$$RFV2Z_k = RFVZ_k$$

When SPFVZ = "N"

(i.e., a single propellant fill valve is to be used for each propellant tank)

Then

$$RFV1Z_k = (RFVZ_k)^{NPZ}$$

$$RFV2Z_k = 1.0$$

When CONVZ = "SQ" or not "SOL"

(i.e., specifications of the type of valve system connecting the two half-systems)

Then

$$BZ_k = RSV2Z_k$$

When CONVZ = "SOL"

Then

$$BZ_k = RSOLCZ_k$$

The overall system reliability can now be determined in terms of the reliability of the various components and the specific arrangement of the components. In general three basic situations are considered:

- (a) repressurization is not required for either half-system
- (b) repressurization is required for the first half-system,
- (c) repressurization is required for both half-systems.

The probability of having a working thruster system available for use when using the first half-system is

$$RE1Z_k = 1.0 - \left\{ 1.0 - RFV2Z_k \cdot RPD1Z_k \cdot RF1Z_k \cdot RST1Z_k \cdot RTH1Z_k \cdot RLTZ_k \right\} \cdot \left\{ 1.0 - BZ_k \cdot RFV2Z_k \cdot RPD2Z_k \cdot RF2Z_k \cdot RST2Z_k \cdot RTH2Z_k \cdot RLTZ_k \right\}$$

and represents the probability of thruster system #1, or thruster system #2 and half-system interconnecting valve functioning properly. Similarly, the probability of having a working thruster system available for use when using the second half-system is

$$RE2Z_k = 1.0 - \left\{ 1.0 - BZ_k \cdot RFV2Z_k \cdot RPD1Z_k \cdot RF1Z_k \cdot RST1Z_k \cdot RTH1Z_k \cdot RLTZ_k \right\} \cdot \left\{ 1.0 - RFV2Z_k \cdot RPD2Z_k \cdot RF2Z_k \cdot RST2Z_k \cdot RTH2Z_k \cdot RLTZ_k \right\}$$

The probability of successful operation of a propellant tank and its associated fill valve, solenoid valve, and lines is given by $R1Z_k$ for the first half-system and $R2Z_k$ for the second half-system. Therefore,

$$R1Z_k = RB1Z_k \cdot RFV1Z_k \cdot RSP1Z_k \cdot RLPPZ_k$$

$$R2Z_k = RB2Z_k \cdot RFV2Z_k \cdot RSP2Z_k \cdot RLPPZ_k$$

$$Q1Z_k = 1.0 - R1Z_k$$

$$Q2Z_k = 1.0 - R2Z_k$$

The reliability of the high pressure tank, fill valve, and squib valve system is given by $DEL1Z_k$ and $DEL2Z_k$ and depends upon the need for repressurization. Therefore,

When $MODE1 < 2$

Then

$$DEL1Z_k = 1.0$$

$$DEL2Z_k = 1.0$$

When $MODE1 = 2$ and $MODE2 < 2$

Then

$$DEL1Z_k = RFVZ_k \cdot RTZ_k \cdot RSV1Z$$

$$DEL2Z_k = 1.0$$

When $MODE1 = 2$ and $MODE2 = 2$

Then

$$DEL1Z_k = RFVZ_k \cdot RTZ_k \cdot RSV1Z$$

$$DEL2Z_k = DEL1Z_k$$

Since there are multiple propellant and pressurant tanks and redundant thruster systems, the reliability of the system is a function of the propellant requirement as a function of time. The model computes the propellant required for each maneuver and thence establishes the reliability in terms of the probability of the propellant being available. The possible ways of achieving six different outcomes, or propellant levels, are considered. Specifically, the probability of having 1/6, 1/3, 1/2, 2/3, 5/6, and full

propellant capability at any instant of time is determined. The way of achieving these outcomes is illustrated in Figures 2-7 where the following nomenclature applies:

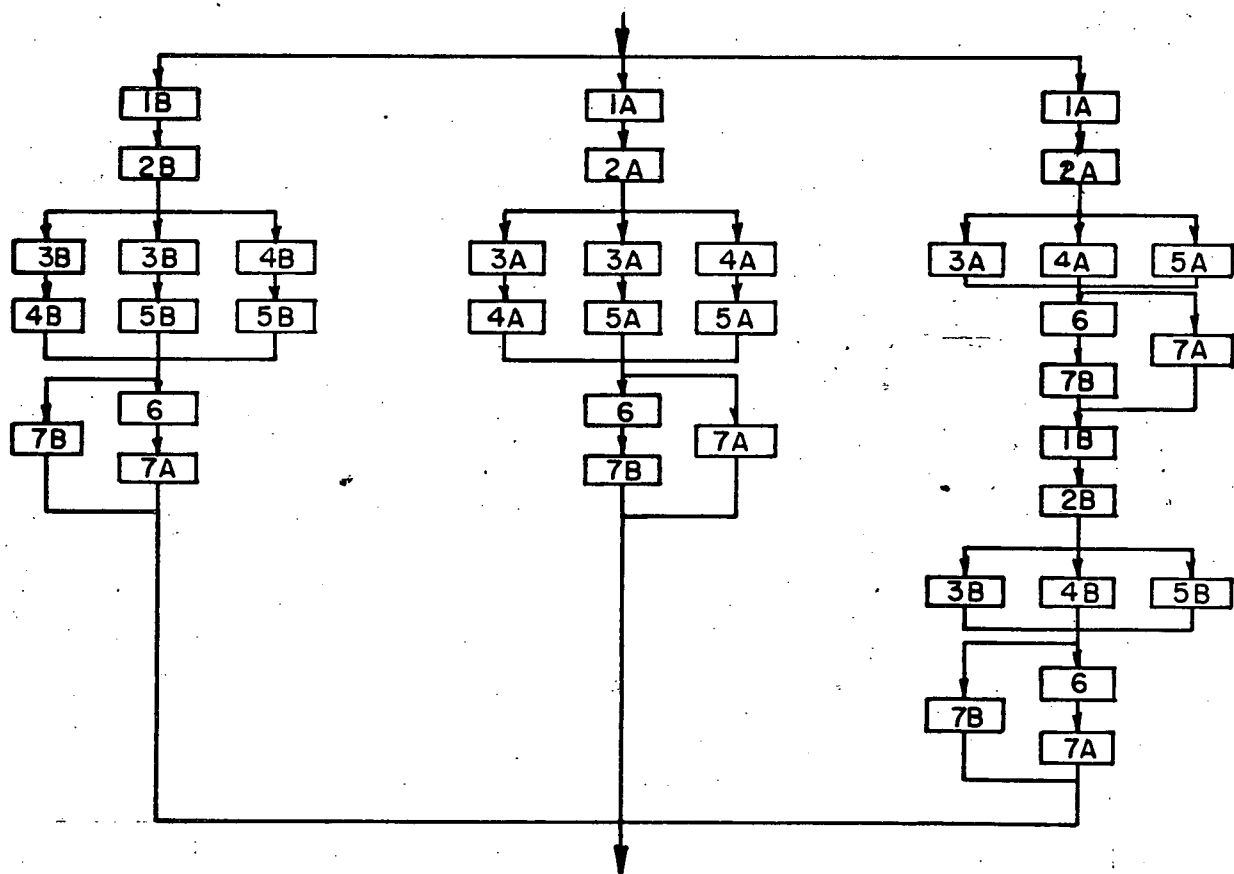
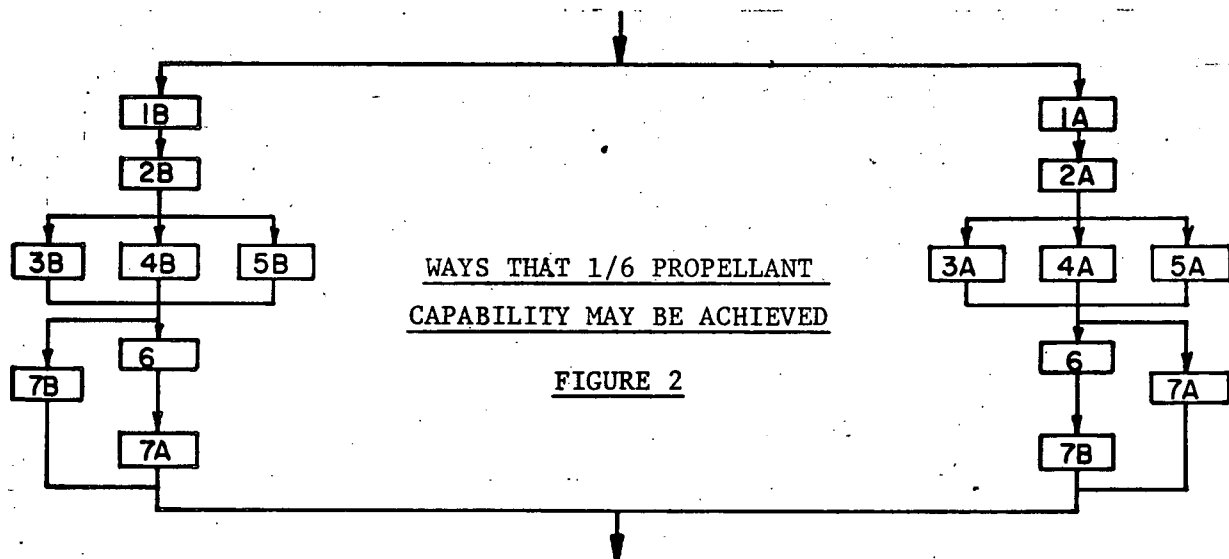
- . A & B - refers to half-system one and two.
- . 1A, & 1B - refers to high pressure tank system, fill valve, and squib valve system.
- . 2A, & 2B - refers to fill valve, lines between squib and propellant tanks, and propellant tanks.
- . 3A, 4A, 5A, 3B, 4B, 5B - refers to the propellant tank bladder, fill valve (A), solenoid valve system, and lines between propellant tanks and fill valve (B).
There are six tank systems; three per half.
- . 6 - refers to the half-system connecting valve system.
- . 7A, 7B - refers to fill valve (B), pressure transducer, filter, orifice, solenoid valve system, and thruster.

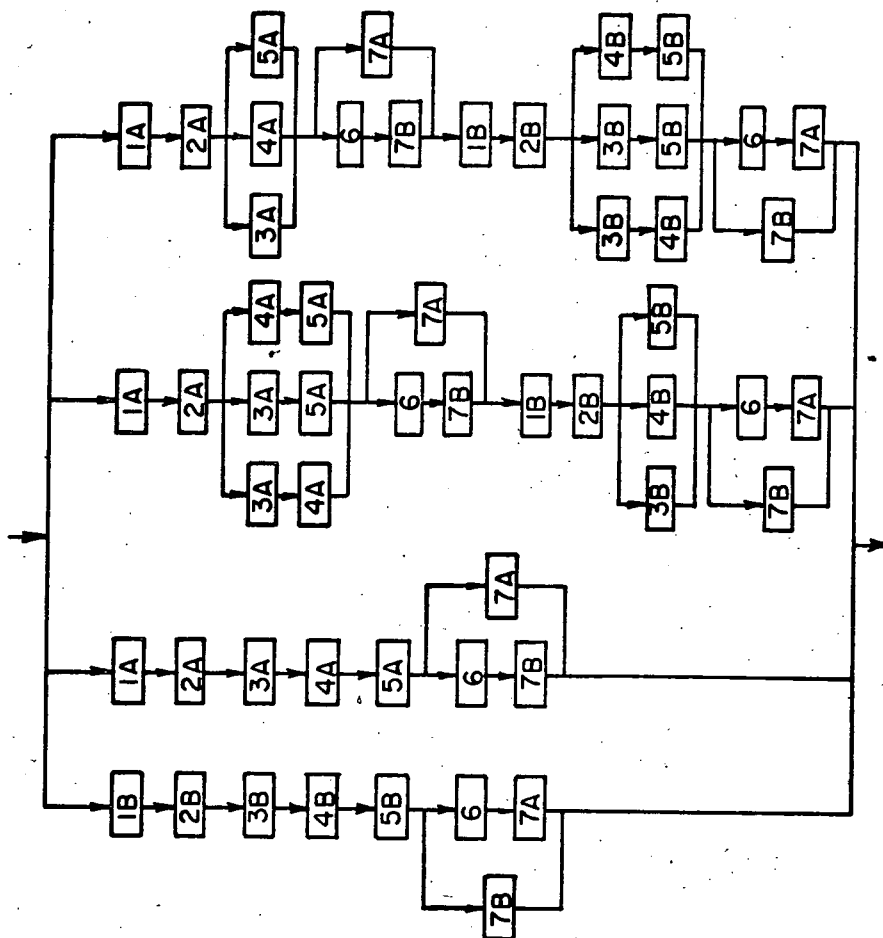
Using figures 2-7 as a guide, the probability of having different levels of propellant available when needed and functioning properly can be established as

$$GZ_k = RLHPZ_k \cdot RFVZ_k \cdot RPTZ_k$$

$$PFZ_{k,1} = \left\{ 3.0 \cdot GZ_k \right\} \cdot \left\{ R1Z_k \cdot Q1Z_k^2 \cdot RE1Z_k \cdot DEL1Z_k \cdot [1.0 - GZ_k \cdot DEL2Z_k + GZ_k \cdot DEL2Z_k \cdot Q2Z_k^3] + R2Z_k \cdot Q2Z_k^2 \cdot RE2Z_k \cdot [1.0 - GZ_k \cdot DEL1Z_k + GZ_k \cdot DEL1Z_k \cdot Q1Z_k^3] \right\}$$

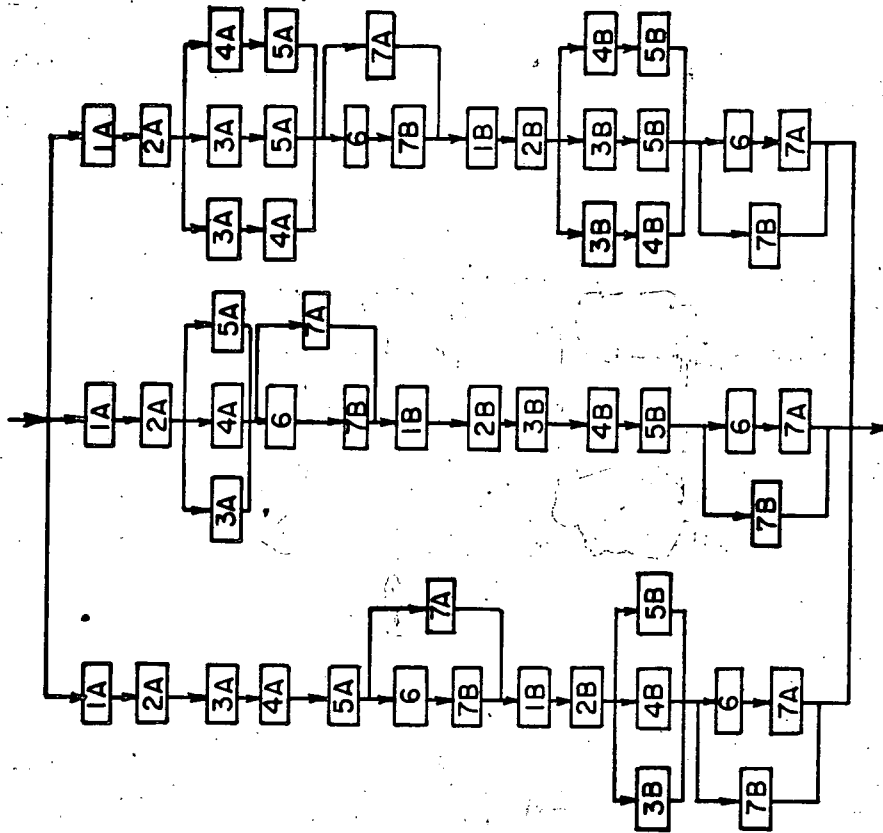
$$PFZ_{k,2} = \left\{ 3.0 \cdot GZ_k \right\} \cdot \left\{ R1Z_k^2 \cdot Q1Z_k \cdot RE1Z_k \cdot DEL1Z_k \cdot [1.0 - GZ_k \cdot DEL2Z_k + GZ_k \cdot DEL2Z_k \cdot Q2Z_k^3] + R2Z_k^2 \cdot Q2Z_k \cdot RE2Z_k \cdot DEL2Z_k \cdot [1.0 - GZ_k \cdot DEL1Z_k + GZ_k \cdot DEL1Z_k \cdot Q1Z_k^3] + 3.0 \cdot R1Z_k \cdot R2Z_k \cdot Q1Z_k^2 \cdot Q2Z_k^2 \cdot RE1Z_k \cdot RE2Z_k \cdot DEL1Z_k \cdot DEL2Z_k \cdot GZ_k \right\}$$





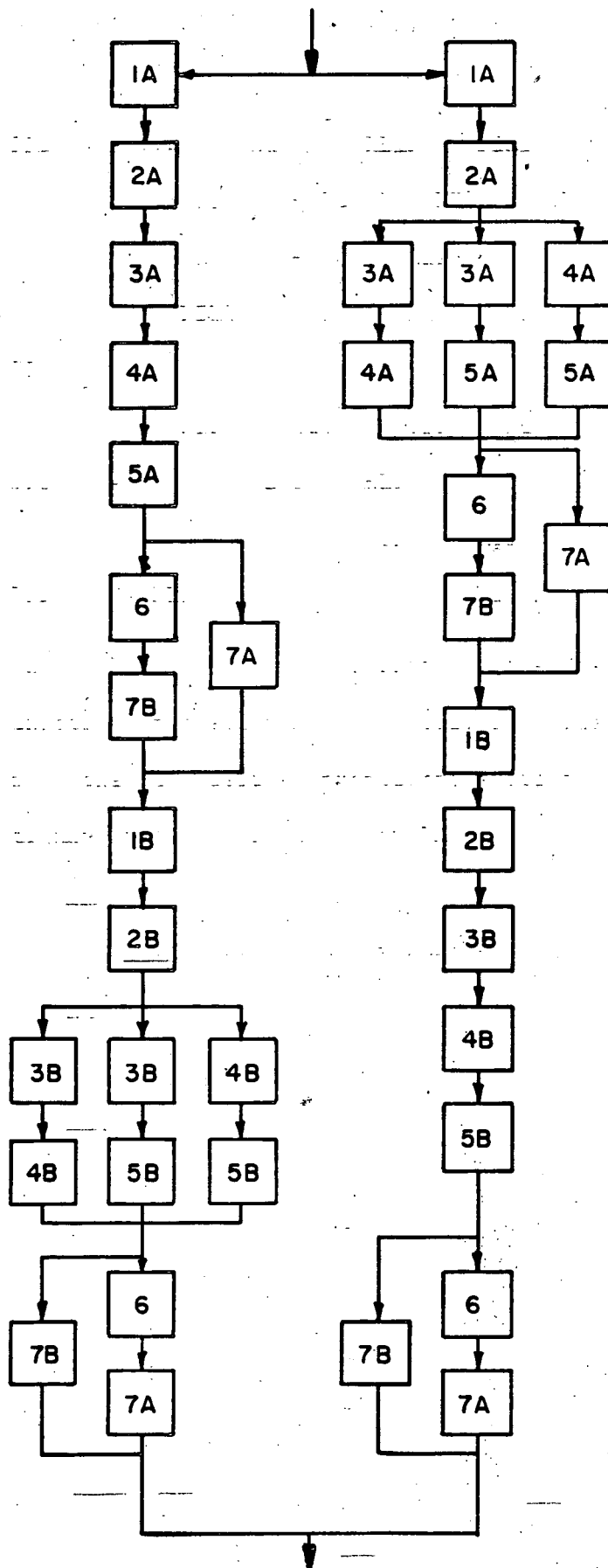
WAYS THAT 1/2 PROPELLANT
CAPABILITY MAY BE ACHIEVED

FIGURE 4

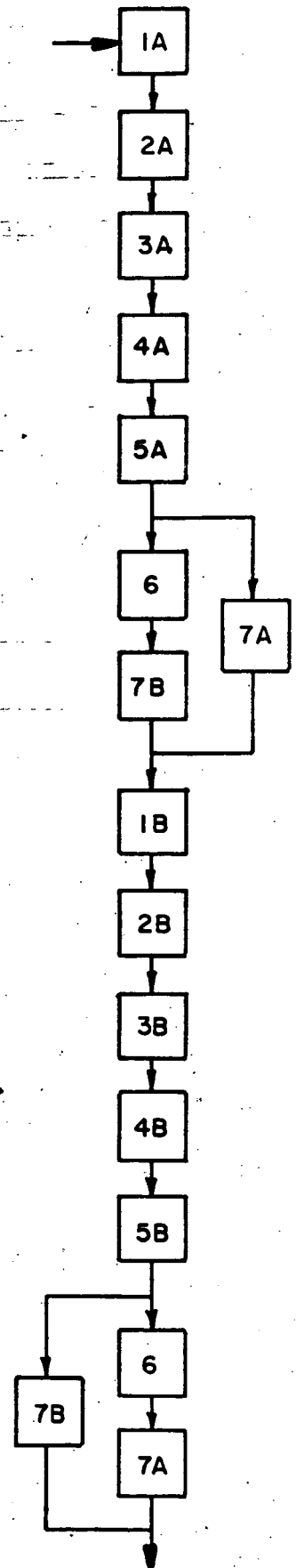


WAYS THAT 2/3 PROPELLANT
CAPABILITY MAY BE ACHIEVED

FIGURE 5



WAYS THAT 5/6 PROPELLANT
CAPABILITY MAY BE ACHIEVED
FIGURE 6



WAYS THAT TOTAL PROPELLANT
CAPABILITY MAY BE ACHIEVED
FIGURE 7

$$PFZ_{k,3} = \left\{ GZ_k \right\} \cdot \left\{ R1Z_k^3 \cdot RE1Z_k \cdot DEL1Z_k \cdot [1.0 - GZ_k \cdot DEL2Z_k + GZ_k \cdot DEL2Z_k \cdot Q2Z_k^3] + R2Z_k^3 \cdot RE2Z_k \cdot DEL2Z_k \cdot [1.0 - GZ_k \cdot DEL1Z_k + GZ_k \cdot DEL1Z_k \cdot Q1Z_k^3] + 9.0 \cdot R1Z_k \cdot R2Z_k \cdot Q2Z_k \cdot RE1Z_k \cdot RE2Z_k \cdot DEL1Z_k \cdot Q1Z_k \cdot DEL2Z_k \cdot GZ_k \cdot [R1Z_k \cdot Q2Z_k + Q1Z_k \cdot R2Z_k] \right\}$$

$$PFZ_{k,4} = \left\{ 3.0 \cdot RE1Z_k \cdot RE2Z_k \cdot GZ_k^2 \cdot DEL1Z_k \cdot DEL2Z_k \cdot R1Z_k \cdot R2Z_k \right\} \cdot \left\{ R1Z_k^2 \cdot Q2Z_k^2 + Q1Z_k^2 \cdot R2Z_k^2 + 3.0 \cdot R1Z_k \cdot Q1Z_k \cdot Q2Z_k \cdot R2Z_k \right\}$$

$$PFZ_{k,5} = \left\{ 3.0 \cdot RE1Z_k \cdot RE2Z_k \cdot GZ_k^2 \cdot DEL1Z_k \cdot DEL2Z_k \cdot R1Z_k^2 \cdot R2Z_k^2 \right\} \cdot \left\{ R1Z_k \cdot Q2Z_k + Q1Z_k \cdot R2Z_k \right\}$$

$$PFZ_{k,6} = RE1Z_k \cdot RE2Z_k \cdot GZ_k^2 \cdot DEL1Z_k \cdot DEL2Z_k \cdot R1Z_k^3 \cdot R2Z_k^3$$

where $PFZ_{k,i}$ is the probability of the system functioning properly and having exactly i propellant tanks available. Therefore, the probability of having more than the desired propellant available when needed and the system functioning properly is given by PMZ_k .

When $HALFZ = 1$

Then $PMZ_k = PM1_k + PM2_k$

When $HALFZ = 2$

Then $PMZ_k = PM2_k$

When $PMZ_k \geq \frac{5.0}{6.0} \cdot PMO \cdot 2.0$ (i.e., at least 1 propellant tank available)

Then $PZ_k = \sum_{IZ=1}^6 PFZ_{k,IZ}$

When $\frac{5.0}{6.0} \cdot PMO \cdot 2.0 > PMZ_k \geq \frac{2.0}{3.0} \cdot PMO \cdot 2.0$ (i.e., at least 2 propellant tanks available)

Then $PZ_k = \sum_{IZ=2}^6 PFZ_{k,IZ}$

When $\frac{2.0}{3.0} \cdot PMO \cdot 2.0 > PMZ_k \geq \frac{1.0}{2.0} \cdot PMO \cdot 2.0$ (i.e., at least 2 propellant tanks available)

Then $PZ_k = \sum_{IZ=3}^6 PFZ_{k,IZ}$

When $\frac{1.0}{2.0} \cdot \text{PMO} \cdot 2.0 > \text{PMZ}_k \geq \frac{1.0}{3.0} \cdot \text{PMO} \cdot 2.0$ (i.e., at least 4 propellant tanks available)

Then $\text{PZ}_k = \sum_{\text{IZ}=4}^6 \text{PFZ}_{k,\text{IZ}}$

When $\frac{1.0}{3.0} \cdot \text{PMO} \cdot 2.0 > \text{PMZ}_k \geq \frac{1.0}{6.0} \cdot \text{PMO} \cdot 2.0$ (i.e., at least 5 propellant tanks available)

Then $\text{PZ}_k = \sum_{\text{IZ}=5}^6 \text{PFZ}_{k,\text{IZ}}$

When $\frac{1.0}{6.0} \cdot \text{PMO} \cdot 2.0 > \text{PMZ}_k \geq 0$ (i.e., all 6 propellant tanks available)

Then $\text{PZ}_k = \text{PFZ}_{k,6}$

In other words, PMZ_k is the reliability of the orbit correction system as a function of the orbit correction maneuver. The overall system reliability takes into account the specific operations of the auxiliary propulsion system; i.e., thrust duration, number of impulses to achieve desired velocity increments, magnitude and timing of velocity increments, etc. The reliability model considers each of the k maneuvers as a different outcome and establishes the probability of achieving each outcome taking into account the various ways in which the outcome can be achieved.

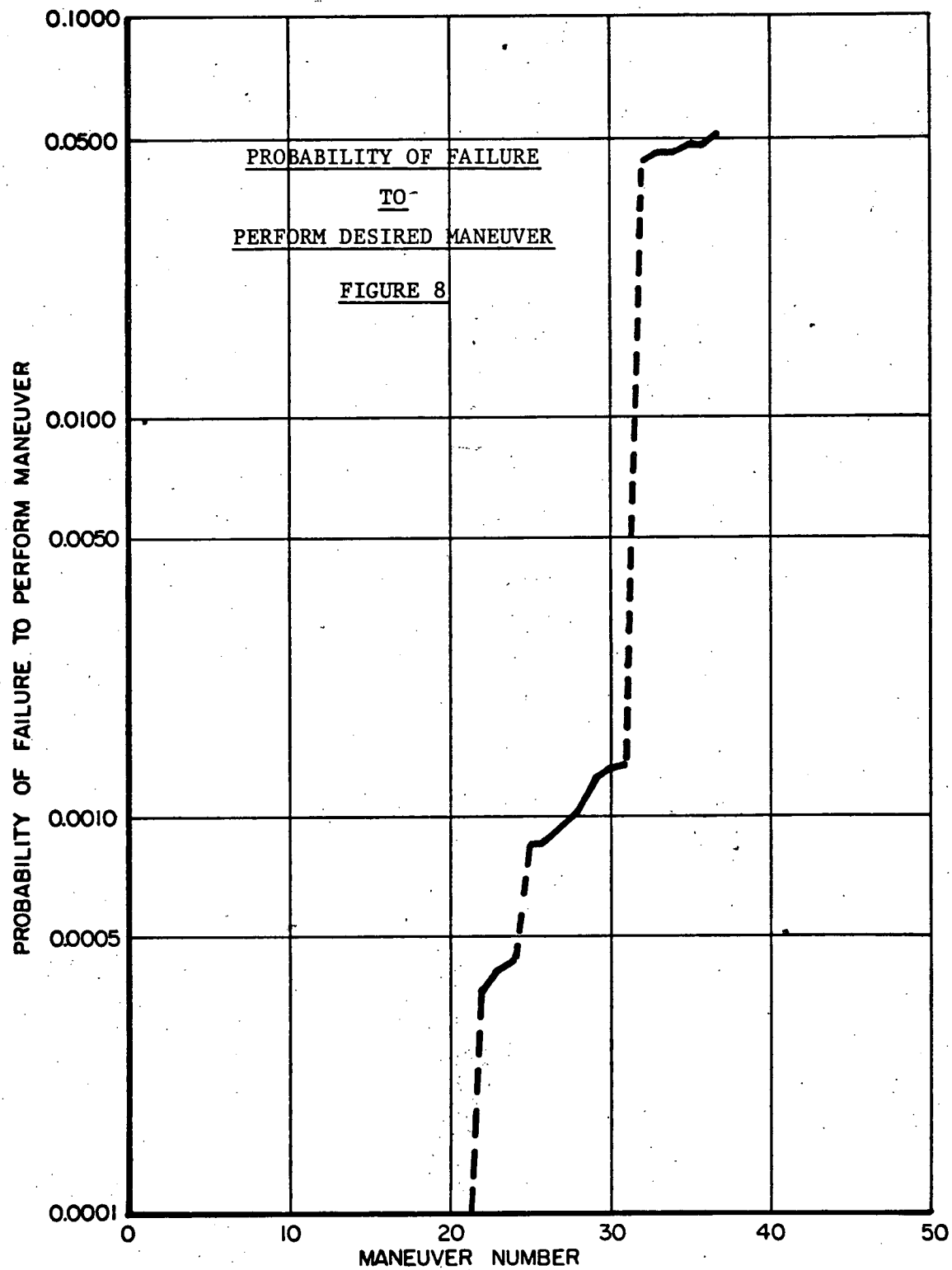
Typical Results

In order to demonstrate the type of results available from this model, a typical mission profile was assumed along with propulsion system characteristics. The set of input data is printed out and is attached as part of Appendix II. The mission evaluated consisted of 39 orbit corrections spaced over a period of approximately one year. Several of the orbit corrections are spaced at intervals of one-half an orbit period while others are separated by tens of days. The computed results are also shown in Appendix II. Only 37

maneuvers are possible due to the performance of the propulsion system. The results of the reliability computations are summarized in Figure 8 which indicates the probability of failing to perform the desired maneuver in terms of the maneuver number. This is one minus the probability of success or the "unreliability" of the system. The specific numbers are unimportant. What is important is the rapid manner in which the probability of a failure increases as the number of maneuvers increases. The reason for this is that early in the mission only one or more propellant tanks need function successfully. In the latter stages of the mission, maneuvers can only be performed if all six propellant tanks have and continue to function properly! The large probability increments ($k=21, 25, 32$) are due to the requirement of additional propellant tanks being available. The small changes in the probability of failure between maneuvers no. 25 & 26, 29 & 30, etc., are due to the fact that the maneuvers occur within a time interval of $1/2$ an orbit period (i.e., a perigee followed by an apogee correction).

GENERAL DISCUSSION

A general methodology for evaluating the reliability of a propulsion system as a function of time or mission objective has been described. The method requires the interaction of a propulsion system performance model with a reliability model. The performance model provides basic timing and cycle data required for the reliability computations and the reliability model provides the basic structure for the manner in which the various mission outcomes or objectives can be achieved. The reliability model thence performs the reliability computations, in terms of



specific equipment configurations, providing probability of success data for achieving each of the desired mission objectives.

When a mission consists of multiple time distributed mission objectives (for example, the previously discussed orbit correction system), the normal procedure for evaluating system reliability at a single point in time loses significance. The reliability of the system after t hours is still an important indicator of overall system performance. However, it is also important to establish the probability of successfully achieving each desired mission objective within the t hours.

The availability of data indicating the probability of successfully achieving each of the desired mission objectives can provide valuable insights for the comparison of system alternatives. In particular, if the relative importance of the various mission objectives is established, a figure of merit can be computed and used to assist with the ranking and comparison of alternatives. The figure of merit is of the form

$$F = \sum_k PZ_k \cdot IMP_k$$

where IMP_k is the relative importance of achieving the k^{th} mission objective. It is normally desirable to choose that system configuration which maximizes F . When cost constraints become important, the above can be utilized to establish a measure of cost effectiveness (CE) such that

$$CE = \frac{F}{C}$$

where C is the total cost associated with the system configuration under

study. The objective is to chose that system configuration which maximizes the value of CE. When costs are spread over a significant period of time, present value concepts should be used so as to take into account the timing of expenditure of funds.

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APPENDIX A: Program Listing

```

REAL LVZ,LCZ,NTZ,LWZ,NWHPZ,LCLZ,LOPZ,LVSZ,LPZ,LPZ,
1NSCZ,LSCZ,NBZ,LBRZ,NPZ,LEZ,NWTZ,NWPZ
REAL*8 MBZ,STDZ,RT2S,ERFC2,ERFC1,ERFC21,DERFC
INTEGER CYCL1Z,CYCL2Z
INTEGER HALFZ

```

```

DATAKS/'S'//,KDS/'DS'//,KDP/'DP'//,KQ/'Q'//,KN/'N'//,KSQ/'SQ'//
DIMENSION ORF(10),DELF(10),DELPE(10),DELV(100),CD(10),A(10),
1STI(100),STIME(100),SDELV(100),STDEL(100),STIM(100)
DIMENSION RFVZ(100),RTZ(100),RPTZ(100),RLHPZ(100),
1TIMEZ(100),RF1TZ(100),RPD1Z(100),RPD2Z(100),PFZ(100,6),
2RF1Z(100),RF2Z(100),CYCL1Z(100),CYCL2Z(100),PZ(100),
3RE1Z(100),RE2Z(100),RSP1Z(100),RST1Z(100),RST2Z(100),
4RSP2Z(100),RTH1Z(100),RTH2Z(100),RB1Z(100),RB2Z(100),BZ(100),
5RLPPZ(100),RLTZ(100),RTHZ(100)

```

```

NAMELIST/INDATL/VEJIN,Z,CFIN,DEN,AT,PFIL,STG,CD,A,DT,DTI,P,DPT,
1PMO,VTK,VTINT,PW,WSC,L,ULV,DELV,PRES,PCMIN,PCIN,DP,TMAX,TLNCH,
2RGAS,G

```

```

NAMELIST/INDATG/TIMEZ,LVZ,LCZ,NTZ,LWZ,NS1Z,PFSZ,
1NWHFZ,CONVZ,NS2Z,LCLZ,LOPZ,LVSZ,VSC,LPZ,LPZ,NSCZ,
2LSCZ,NBZ,LBRZ,NPZ,LBZ,MBZ,STDZ,NWTZ,NWPZ,SPFVZ,VSC,VST,VSP

```

```

WRITE(6,70)

```

```

70 FORMAT('1INPUT DATA')

```

```

C FOR STEADY STATE MODE USE PW=1.0E+10 SEC.

```

```

READ(5,INDATL)

```

```

WRITE(6,INDATL)

```

```

READ(5,INDATG)

```

```

WRITE(6,INDATG)

```

```

C AT INPUT DIVIDE THE FOLLOWING VARIABLES BY 2

```

```

PMO=PMO/2.

```

```

VTK=VTK/2.

```

```

ULV=ULV/2.

```

```

VTINT=VTINT/2.

```

```

C COMPLEMENT OF THE ERROR FUNCTION

```

```

RT2S=1.414 13562 3731D0*STDZ

```

```

ERFC2=DERFC((2.D0-MBZ)/RT2S)

```

```

ERFC1=DERFC((1.D0-MBZ)/RT2S)

```

```

ERFC21=ERFC2/ERFC1

```

```

CALL STINT(0.,0.,0.,0.,-1,NGRIPE,0,0)

```

```

IF(NGRIPE.NE.0)GO TO 100

```

```

WRITE(6,86)

```

```

86 FORMAT(' END DATA',///)

```

```

WRITE(6,83)

```

```

83 FORMAT(' LIST OF VARIABLES WITH CORRESPONDING UNITS',/)

```

```

WRITE(6,82)

```

```

82 FORMAT(' AT=THROAT AREA(SQ MET) PGO=INIT TANK PRES(N/SQ MET) STG=S
1TAGE NUMBER CD=ORIFICE COEF A=ORIFICE OR VALVE FLOW AREA (SQ MET)'
2/'WSC=SPACECRAFT MASS (KG) ULV=GAS BOT VOLUME (CU MET) DELV=DELTA
3V (MET/SEC) ')

```

```

WRITE(6,84)

```

```

84 FORMAT(' Z=CCMPRES FACT CF=THRUST COEF DEN=PROP DENS (K/CUMET)
1DT=LOOP TIME INCR(SEC)DTI=LOOP2 TIME INC (SEC) P=PRES BOT EXPAN
2EXP'/' DPT=INTERNAL TANK PRES DROP (N/SQ MET) PMO=PRCP MASS (KG)
3R=PROP TANK RADIUS (MET) PW=PULSE WIDTH (SEC)')

```

```

WRITE(6,81)

```

```

81 FORMAT('VTK=TANK VOL(CU MET)VTINT=INTERNAL TANK DISPLACEMENT (CU
1MET) VG2 + VG3 = 2ND ST6 GAS VOL (CUMET) A(2)=ORIFICE AREA (CUMET)

```

```

2) ')
PMI=PMO
C*** THIS ROUTINE ADJUSTS THE TANK PRESSURE FOR LAUNCH TEMPERATURE
TEMP=TMAX
CALL STINT(TEMP,0.,0.,DEN,1,NGRIPE,5,5)
IF(NGRIPE.NE.0) GO TO 100
DENO=DEN
VOLG=VTK-VTINT-PMO/DENO
DEN=0.
TEMP=TLNCH
CALL STINT(TEMP,0.,0.,DEN,1,NGRIPE,5,5)
IF(NGRIPE.NE.0) GO TO 100
DELVCL=(PMO/DENO)*(1.-DENO/DEN)
VGO=VOLG+DELVOL
PGO=PFIL*VOLG*TLNCH/(TMAX*VGO)
C2=Z/DEN
C THIS ROUTINE SIZES THE FLOW ORIFICE
VEJ=VEJIN
CF=CFIN
AP=.7853975*DP*DP
PG=PGO
DPT=DPT*6897.4862
DO 131 M=1,5000
SUMA=0.
DO 10 I=1,10
IF(CD(I).EQ.0.) GO TO 101
IF(A(I).EQ.0.) GO TO 101
ORF(I)=CD(I)*CD(I)*A(I)*A(I)
10 SUMA=SUMA+(1.-ORF(I))/(AP*AP)/(ORF(I)*2.*DEN)
101 C3=SUMA
KM=I-1
CSTAR=VEJ/CF
C1=CSTAR/AT
CONST=(C1*C1)-4.*C3*(DPT-PG)
FM=(-C1+SQRT(CONST))/(2.*C3)
IF(FM.LE.0.) GO TO 114
PC=FM*C1
CALL STINT(PC,0.,0.,VEJ,1,NGRIPE,2,2)
IF(NGRIPE.NE.0) GO TO 100
CALL STINT(PC,0.,0.,CF,1,NGRIPE,3,3)
IF(NGRIPE.NE.0) GO TO 100
IF(PC.GE.PCIN) GO TO 133
A(1)=A(1)+.5E-08
IF(A(1).LE.AP) GO TO 131
A(1)=AP
GO TO 133
131 CONTINUE
133 DOR=SQRT(A(1)*1.274324)
DO 129 N=1,KM
DELP(N)=(FM*FM)*(1.-ORF(N)/(AP*AP))/(ORF(N)*2.*DEN)
129 DELPE(N)=DELP(N)/6897.4862
KI=1
HALFZ=1
MODE1=0
MODE2=0
2 VEJ=VEJIN

```

```

IERR=0
CF=CFIN
TIM=0.
SUM=0.
ICTR=0
TDEL=0.
TI=0.
MODE=0
RESTIM=0.
PM=PMO
C*** L IS THE NUMBER OF MANUEVERS
DO 40 K=KI,L
TIMEP=0.
BTIME=RESTIM
RESTIM=0.
DELTAV=0.
DELN=0.
C THIS LOOP IS ONE PULSE
DO 30 J=1,10000
BTIME=BTIME+TIMEP
C THIS IS THE FIRST STAGE OF BLOWDOWN
DO 20 I=1,10000
IF(MODE.EQ.2) GO TO 115
IF(HALFZ.EQ.2) GO TO 112
MODE1=0
MODE2=0
113 IF(STG.EQ.1.) GO TO 15
IF(PG-PRES) 11,11,15
11 VGO=VGO+SUM*C2+ULV
PGO=PFIL
SUM=0.
PMO=PM
MODE=2
C THIS IS BOTH STAGES OF BLOWDOWN
15 CSTAR=VEJ/CF
C1=CSTAR/AT
C THE EXPONENT WAS EXPERIMENTALLY DETERMINED
PG=PGO*(VGO/(VGO+SUM*C2))**P
PCT=(PMI-PM)/PMI
C THE TANK INTERNAL PRESSURE GRADIENT IS A FUNCTION OF REMAINING PROPELLANT
CALL STINT(PCT,0.,0.,DPT,1,NGRIPE,1,1)
DPT=DPT*6897.486
IF(NGRIPE.NE.0) GO TO 100
CONST=(C1*C1)-4.*C3*(DPT-PG)
IF(CONST.LE.0.) WRITE(6,65)
65 FORMAT(' LOOK UP ERROR')
FM=(-C1+SQRT(CONST))/(2.*C3)
IF(FM.LE.0.) GO TO 21
SUM=SUM+DT*FM
PM=PMO-SUM
IF(PM.LE.0.) GO TO 21
TIME=DT*I
TIMEP=TIME
PC=FM*C1
IF(PC.LE.PCMIN) GO TO 21
C THIS CURVE VARIES FOR DIFFERENT THRUSTERS

```

```

CALL STINT(PC,0.,0.,CF,1,NGRIPE,3,3)
IF(NGRIPE.NE.0)GO TO 100
CALL STINT(PC,0.,0.,VEJ,1,NGRIPE,2,2)
IF(NGRIPE.NE.0)GO TO 100
C THIS CURVE VARIES FOR DIFFERENT PULSE MODES
IF(PW.EQ.1.E+10)GO TO 8
PN=J
CALL STINT(PN,0.,0.,EFF,1,NGRIPE,4,4)
IF(NGRIPE.NE.0)GO TO 100
VEJ=VEJ*EFF
8 BIT=FM*VEJ*DT
TI=TI+BIT
THR=FM*VEJ
SPI=VEJ/9.8
IF(PW.NE.1.E+10)GO TO 9
DELTAV=DELTAV+VEJ*ALOG((WSC+PM+FM*DT)/(WSC+PM))
IF(DELTAV.GE.DELV(K))GO TO 31
9 IF(MCDE.EQ.2)GO TO 111
C THIS FOR FIRST BLOWDOWN
IF(K.NE.1)GO TO 111
IF(J.NE.1)GO TO 111
IF(I.NE.1)GO TO 111
POR=FM*PM*(1.-ORF(1)/(AP*AP))/(ORF(1)*2.*DEN)
PINLET=PG-DPT-POR
WRITE(6,69)
69 FORMAT('1INITIAL CONDITIONS',//)
WRITE(6,59)A(1)
59 FORMAT(' ORIFICE AREA = ',E11.4,' SQ MET',/)
WRITE(6,62)DOR
62 FORMAT(' ORIFICE DIAMETER = ',E11.4,' SQ MET',/)
WRITE(6,64)PRES
64 FORMAT(' PRESSURE AT REPRESSURIZATION = ',E12.4,' N/SQ MET',/)
IF(A(2).NE.0.)WRITE(6,60)DELPE(1)
60 FORMAT(' ORIFICE PRES DROP = ',F5.0,' PSI',/)
IF(A(2).NE.0.)WRITE(6,58)PINLET
58 FORMAT(' PINLET = ',E12.4,' N/SQ M',/)
WRITE(6,61)
61 FORMAT(' MANEUVER',6X,'PROP',12X,' TANK',12X,' CHAM',14X,
1 ' THRUST',16X,' VEJ',15X,' ISP',11X,' FLOW'
2 ' ',15X,' NUMBER',7X,' LEFT',12X,' PRES',12X,' PRES',68X,' RATE
3 ' ',15X,' (KG)',10X,' (N/SQ M)',8X,' (N/SQ M)',14X,' (N)',15X,' (M/SEC)
4 ' ',12X,' (SEC)',8X,' (KG/SEC)'//)
WRITE(6,71)K,PM,PG,PC,THR,VEJ,SPI,FM
71 FORMAT(4X,I3,4X,3(E12.4,4X),E17.4,4X,E17.5,4X,F10.2,4X,E12.4,/)
111 IF(I*DT.GE.PW)GO TO 19
GO TO 20
112 MODE1=2
MODE2=0
GO TO 113
115 IF(HALFZ.EQ.2)GO TO 116
MODE1=2
MODE2=0
GO TO 15
116 MODE1=2
MODE2=2
GO TO 15

```

```

20 CONTINUE
19 PBIT=SUM*VEJ
   DELTAV=DELTAV+VEJ*ALOG((WSC+PM+FM*DT)/(WSC+PM))
   IF(DELTAV.GE.DELV(K))GO TO 31
30 CONTINUE
   RESTIM=BTIME+TIMEP
31 NJ=J
   IF(HALFZ.EQ.2)GO TO 1000
C NUMBER OF CYCLES OF THE DELTA V THRUSTERS; HALFZ=1
   IF(K.EQ.1)GO TO 1010
   CYCL1Z(K)=CYCL1Z(K-1)+NJ
   CYCL2Z(K)=0
   GO TO 1064
1010 CYCL1Z(K)=NJ
   CYCL2Z(K)=0
   GO TO 1064
C NUMBER OF CYCLES OF THE DELTA V THRUSTERS; HALFZ=2
1000 IF(K.EQ.1)GO TO 1016
   CYCL1Z(K)=CYCL1Z(K-1)
   CYCL2Z(K)=CYCL2Z(K-1)+NJ
   GO TO 1064
1016 CYCL1Z(K)=0
   CYCL2Z(K)=NJ
1064 TDEL=TDEL+DELTAV
   POR=FM*FM*(1.-ORF(1)/(AP*AP))/(ORF(1)*2.*DEN)
   PINLET=PG-DPT-POR
   IF(ICTR.EQ.0)GO TO 16
   IF(ICTR.GE.54)GO TO 16
6 WRITE(6,71)K,PM,PG,PC,THR,VEJ,SPI,FM
   ICTR=ICTR+2
C SAVE THE FOLLOWING VARIABLES FOR LATER PRINTING
   STI(K)=TI
   IF(NJ.GT.1)STIME(K)=BTIME
   IF(NJ.EQ.1)STIME(K)=TIME
   SDELV(K)=DELTAV
   STDEL(K)=TDEL
   IF(NJ.GT.1)TIME=BTIME
   TIM=TIM+TIME
   STIM(K)=TIM
   NK=K
   TIMEZ(K)=24.*TIMEZ(K)
C RELIABILITY OF FILL VALVES
1001 RFVZ(K)=1.-(1.-EXP(-LVZ*TIMEZ(K)*1.0E-6))*(1.-EXP(-LCZ*TIMEZ(K)
1*1.0E-06))
C RELIABILITY OF HIGH PRESSURE TANK SYSTEM
   RTZ(K)=EXP(-NTZ*LWZ*TIMEZ(K)*1.0E-06)
C RELIABILITY OF SQUIB VALVE SYSTEM (SV1)
   RSV1Z=1.-(1.-PFSZ)**NS1Z
C PROPELLANT TANK WELD RING RELIABILITY
   RPTZ(K)=EXP(-LWZ*TIMEZ(K)*1.0E-06)
C RELIABILITY OF WELDED CONNECTIONS BETWEEN SQUID VALVE (SV1)
C AND PRESSURANT AND PROPELLANT TANKS
   RLHPZ(K)=EXP(-NWHFZ*LWZ*TIMEZ(K)*1.0E-06)
C RELIABILITY OF SQUIB VALVE SYSTEM (SV2)
   IF(CONVZ.NE.KSQ)GO TO 1002
   RSV2Z=1.-(1.-PFSZ)**NS2Z

```

```

      GO TO 1003
C RELIABILITY OF SOLENOID VALVE SYSTEM (SOLC)
1002 RCSZ=EXP(-LCLZ*1.0E-06)
      ROSZ=EXP(-LOPZ*1.0E-06 -LVSZ*TIMEZ(K)*1.0E-06)
      IF(VSC.EQ.KS)GO TO 1004
      IF(VSC.EQ.KDS)GO TO 1005
      IF(VSC.EQ.KDP)GO TO 1006
      IF(VSC.EQ.KQ)GO TO 1007
C QUAD CONNECTED VALVE SYSTEM
      RSOLCZ=(1.-(1.-RCSZ)*(1.-RCSZ))**2-(1.-ROSZ*ROSZ)**2
      GO TO 1008
C SINGLE VALVE SYSTEM
1004 RSOLCZ=ROSZ+RCSZ-1.
      GO TO 1008
C DUEL SERIES VALVE SYSTEM
1005 RSOLCZ=RCSZ*RCSZ-(1.-ROSZ)*(1.-ROSZ)
      GO TO 1008
C DUEL PARALLEL VALVE SYSTEM
1006 RSOLCZ=ROSZ*ROSZ-(1.-RCSZ)*(1.-RCSZ)
      GO TO 1008
C QUAD VALVE SYSTEM
1007 RSOLCZ=(1.-(1.-ROSZ)*(1.-ROSZ))**2-(1.-RCSZ*RCSZ)**2
C RELIABILITY OF PRESSURE TRANSDUCER
1008 IF(HALFZ.EQ.2)GO TO 1009
C HALFZ EQUALS ONE
      RPD1Z(K)=EXP(-LPZ*(TIM/3600.)*1.0E-06)
      RPD2Z(K)=1.
C RELIABILITY OF FILTER ASSEMBLY; HALFZ=1
      RF1TZ(K)=EXP(LFZ*(TIM/3600.)*1.0E-06)
      RF1Z(K)=RF1TZ(K)*EXP(-LWZ*TIMEZ(K)*1.0E-06)
      RF2Z(K)=EXP(-LWZ*TIMEZ(K)*1.0E-06)
      GO TO 1011
C HALFZ EQUALS TWO
1009 IF(K.EQ.1)GO TO 1012
      RPD1Z(K)=RPD1Z(K-1)
      GO TO 1013
1012 RPD1Z(K)=1.
1013 RPD2Z(K)=EXP(-LPZ*(TIM/3600.)*1.0E-06)
C RELIABILITY OF FILTER ASSEMBLY; HALFZ=2
      IF(K.EQ.1)GO TO 1014
      RF1TZ(K)=RF1TZ(K-1)
      GO TO 1015
1014 RF1TZ(K)=1.
1015 RF1Z(K)=RF1TZ(K)*EXP(-LWZ*TIMEZ(K)*1.0E-06)
      RF2Z(K)=EXP(-LFZ*(TIM/3600.)*1.0E-06 -LWZ*TIMEZ(K)*1.0E-06)
C RELIABILITY OF THRUSTER SOLENOID VALVE SYSTEM
C PROBABILITY OF NO CLOSED FAILURE OF A SINGLE VALVE
1011 RC1Z=EXP(-LCLZ*CYCL1Z(K)*1.0E-06)
      RC2Z=EXP(-LCLZ*CYCL2Z(K)*1.0E-06)
C PROBABILITY OF NO OPEN FAILURE OR LEAK PAST VALVE SEAT
      RO1Z=EXP(-LOPZ*CYCL1Z(K)*1.0E-06-LVSZ*TIMEZ(K)*1.0E-06)
      RO2Z=EXP(-LOPZ*CYCL2Z(K)*1.0E-06-LVSZ*TIMEZ(K)*1.0E-06)
      IF(VST.EQ.KS)GO TO 1017
      IF(VST.EQ.KDS)GO TO 1018
      IF(VST.EQ.KDP)GO TO 1019
      IF(VST.EQ.KQ)GO TO 1020

```

C QUAD CONNECTED VALVE SYSTEM

$$RST1Z(K) = (1. - (1. - RC1Z) * (1. - RC1Z)) ** 2 - (1. - RO1Z * RO1Z) ** 2$$

$$RST2Z(K) = (1. - (1. - RC2Z) * (1. - RC2Z)) ** 2 - (1. - RO2Z * RO2Z) ** 2$$

GO TO 1021

C SINGLE VALVE SYSTEM

1017 $RST1Z(K) = RO1Z + RC1Z - 1.$ $RST2Z(K) = RO2Z + RC2Z - 1.$

GO TO 1021

C DUEL SERIES VALVE SYSTEM

1018 $RST1Z(K) = RC1Z * RC1Z - (1. - RO1Z) * (1. - RO1Z)$ $RST2Z(K) = RC2Z * RC2Z - (1. - RO2Z) * (1. - RO2Z)$

GO TO 1021

C DUEL PARALLEL VALVE SYSTEM

1019 $RST1Z(K) = RO1Z * RO1Z - (1. - RC1Z) * (1. - RC1Z)$ $RST2Z(K) = RO2Z * RO2Z - (1. - RC2Z) * (1. - RC2Z)$

GO TO 1021

C QUAD VALVE SYSTEM

1020 $RST1Z(K) = (1. - (1. - RO1Z) * (1. - RO1Z)) ** 2 - (1. - RC1Z * RC1Z) ** 2$ $RST2Z(K) = (1. - (1. - RO2Z) * (1. - RO2Z)) ** 2 - (1. - RC2Z * RC2Z) ** 2$

C THRUSTER RELIABILITY

1021 IF (HALFZ.EQ.2) GO TO 1022

 $RTHZ(K) = \exp(-NSCZ * LSCZ * (TIM/3600.)) * 1.0E-06$ $RTH2Z(K) = \exp((-NBZ * LBRZ * TIMEZ(K) - 2. * LWZ * TIMEZ(K)) * 1.0E-06)$ $RTH1Z(K) = RTHZ(K) * RTH2Z(K)$

GO TO 1023

1022 IF (K.EQ.1) GO TO 1024

 $RTHZ(K) = RTHZ(K-1)$

GO TO 1025

1024 $RTHZ(K) = 1.$ 1025 $TEMP = (-NBZ * LBRZ * TIMEZ(K) - 2. * LWZ * TIMEZ(K)) * 1.0E-06$ $RTH1Z(K) = RTHZ(K) * \exp(TEMP)$ $RTH2Z(K) = \exp(((TEMP/1.0E-06) - NSCZ * LSCZ * TIM/3600.)) * 1.0E-06)$

C PROPELLANT TANK BLADDER RELIABILITY

1023 IF (MODE1.EQ.2) GO TO 1026

 $RB1Z(K) = \exp(-NPZ * LBZ * TIMEZ(K)) * 1.0E-06$ $RB2Z(K) = RB1Z(K)$

GO TO 1027

1026 IF (MCDE2.EQ.2) GO TO 1028

 $RB1Z(K) = (\exp(-NPZ * LBZ * TIMEZ(K)) * 1.0E-06) * \text{ERFC}21$ $RB2Z(K) = \exp(-NPZ * LBZ * TIMEZ(K)) * 1.0E-06$

GO TO 1027

1028 $RB1Z(K) = (\exp(-NPZ * LBZ * TIMEZ(K)) * 1.0E-06) * \text{ERFC}21$ $RB2Z(K) = RB1Z(K)$

C RELIABILITY OF PRESSURANT AND PROPELLANT TANK SOLENOID VALVE SYSTEM

1027 IF (VSP.EQ.KS) GO TO 1029

IF (VSP.EQ.KDS) GO TO 1030

IF (VSP.EQ.KDP) GO TO 1031

IF (VSP.EQ.KQ) GO TO 1032

C QUAD CONNECTED VALVE SYSTEM

 $RSP1Z(K) = (1. - (1. - RC1Z) * (1. - RC1Z)) ** 2 - (1. - RO1Z * RO1Z) ** 2$ $RSP2Z(K) = (1. - (1. - RC2Z) * (1. - RC2Z)) ** 2 - (1. - RO2Z * RO2Z) ** 2$

GO TO 1033

C SINGLE VALVE SYSTEM

1029 $RSP1Z(K) = RO1Z + RC1Z - 1.$ $RSP2Z(K) = RO2Z + RC2Z - 1.$

GO TO 1033

C DUEL SERIES VALVE SYSTEM

1030 $RSP1Z(K) = RC1Z * RC1Z - (1. - RO1Z) * (1. - RO1Z)$
 $RSP2Z(K) = RC2Z * RC2Z - (1. - RO2Z) * (1. - RO2Z)$
 GO TO 1033

C DUEL PARALLEL VALVE SYSTEM

1031 $RSP1Z(K) = RO1Z * RO1Z - (1. - RC1Z) * (1. - RC1Z)$
 $RSP2Z(K) = RO2Z * RO2Z - (1. - RC2Z) * (1. - RC2Z)$
 GO TO 1033

C QUAD VALVE SYSTEM

1032 $RSP1Z(K) = (1. - (1. - RO1Z) * (1. - RC1Z)) ** 2 - (1. - RC1Z * RC1Z) ** 2$
 $RSP2Z(K) = (1. - (1. - RO2Z) * (1. - RC2Z)) ** 2 - (1. - RC2Z * RC2Z) ** 2$

C RELIABILITY OF WELDED CONNECTIONS BETWEEN PROPELLANT TANK

C SOLENOID VALVE AND THRUSTER

1033 $RLTZ(K) = EXP(-NWTZ * LWZ * TIMEZ(K) * 1.0E-06)$

C RELIABILITY OF WELDED CONNECTIONS BETWEEN PROPELLANT TANK

C AND SOLENOID VALVE SYSTEM

$RLPPZ(K) = EXP(-NWPZ * LWZ * TIMEZ(K) * 1.0E-06)$

C GENERAL SYSTEM RELIABILITY

1003 IF(SPPVZ.EQ.KN) GO TO 1034

$RFV1Z = 1.$

$RFV2Z = RFVZ(K)$

GO TO 1035

1034 $RFV1Z = RFVZ(K) ** NPZ$

$RFV2Z = 1.$

1035 IF(CONVZ.NE.KSQ) GO TO 1036

$BZ(K) = RSV2Z$

GO TO 1037

1036 $BZ(K) = RSOLCZ$

C REPRESSURIZATION NOT REQUIRED FOR EITHER HALF-SYSTEM

1037 $RE1Z(K) = 1. - (1. - RFV2Z * RPD1Z(K) * RF1Z(K) * RST1Z(K) * RTH1Z(K) * 1RLTZ(K)) * (1. - BZ(K) * RFV2Z * RPD2Z(K) * RF2Z(K) * RST2Z(K) * 2RTH2Z(K) * RLRTZ(K))$

$RE2Z(K) = 1. - (1. - BZ(K) * RFV2Z * RPD1Z(K) * RF1Z(K) * RST1Z(K) * RTH1Z(K) * 1*RLTZ(K)) * (1. - RFV2Z * RPD2Z(K) * RF2Z(K) * RST2Z(K) * RTH2Z(K) * 2RLTZ(K))$

C REPRESSURIZATION REQUIRED FOR FIRST HALF-SYSTEM

$R1Z = RB1Z(K) * RFV1Z * RSP1Z(K) * RLPPZ(K)$

$R2Z = RB2Z(K) * RFV2Z * RSP2Z(K) * RLPPZ(K)$

C REPRESSURIZATION REQUIRED FOR BOTH HALF-SYSTEMS

$Q1Z = 1. - R1Z$

$Q2Z = 1. - R2Z$

IF(MODE1.EQ.2) GO TO 1038

$DEL1Z = 1.$

$DEL2Z = 1.$

GO TO 1039

1038 IF(MODE2.EQ.2) GO TO 1040

$DEL1Z = RFVZ(K) * RTZ(K) * RSV1Z$

$DEL2Z = 1.$

GO TO 1039

1040 $DEL1Z = RFVZ(K) * RTZ(K) * RSV1Z$

$DEL2Z = DEL1Z$

C PROBABILITY OF HAVING DEFFERENT LEVELS OF PROPELLANT

C AVAILABLE WHEN NEEDED AND FUNCTIONING PROPERLY

1039 $GZ = RLHPZ(K) * RFVZ(K) * RPTZ(K)$

$PFZ(K,1) = (3. * GZ) * (R1Z * Q1Z * Q1Z * RE1Z(K) * DEL1Z * (1. - GZ * 1DEL2Z + GZ * DEL2Z * Q2Z * Q2Z * Q2Z) + R2Z * Q2Z * RE2Z(K) *$

```

2(1.-GZ*DEL1Z+GZ*DEL1Z*Q1Z*Q1Z*Q1Z))
PFZ(K,2)=(3.*GZ)*(R1Z*R1Z*Q1Z*RE1Z(K)*DEL1Z*(1.-GZ*DEL2Z+
1GZ*DEL2Z*Q2Z*Q2Z*Q2Z)+R2Z*R2Z*Q2Z*RE2Z(K)*DEL2Z*
2(1.-GZ*DEL1Z+GZ*DEL1Z*Q1Z*Q1Z*Q1Z)+3.*R1Z*R2Z*Q1Z
3*Q1Z*Q2Z*Q2Z*RE1Z(K)*RE2Z(K)*DEL1Z*DEL2Z*GZ)
PFZ(K,3)=GZ*(R1Z*R1Z*R1Z*RE1Z(K)*DEL1Z*(1.-GZ*DEL2Z+
1GZ*DEL2Z*Q2Z*Q2Z*Q2Z)+R2Z*R2Z*R2Z*RE2Z(K)*DEL2Z*(1.-GZ
2*DEL1Z+GZ*DEL1Z*Q1Z*Q1Z*Q1Z)+9.*R1Z*R2Z*Q1Z*Q2Z
3*RE1Z(K)*RE2Z(K)*DEL1Z*DEL2Z*GZ*(R1Z*Q2Z+Q1Z*R2Z))
PFZ(K,4)=(3.*RE1Z(K)*RE2Z(K)*GZ*GZ*DEL1Z*DEL2Z*R1Z*R2Z)
1*(R1Z*R1Z*Q2Z*Q2Z+Q1Z*Q1Z*R2Z*R2Z+3.*R1Z*R2Z*
2Q1Z*Q2Z)
PFZ(K,5)=(3.*RE1Z(K)*RE2Z(K)*GZ*GZ*DEL1Z*DEL2Z*R1Z*R1Z*
1R2Z*R2Z)*(R1Z*Q2Z+Q1Z*R2Z)
PFZ(K,6)=RE1Z(K)*RE2Z(K)*GZ*GZ*DEL1Z*DEL2Z*R1Z*R1Z*R1Z
1*R2Z*R2Z*R2Z

```

C PROBABILITY OF HAVING MORE THAN THE DESIRED PROPELLANT

C AVAILABLE WHEN NEEDED AND THE SYSTEM FUNCTIONING PROPERLY

IF(HALFZ.EQ.2) GO TO 1041

PMZ=PM+PMO

GO TO 1042

1041 PMZ=PM

1042 FSE=(5./6.)*PMO*2.

TTE=(2./3.)*PMO*2.

OTE=(1./3.)*PMO*2.

OSE=(1./6.)*PMO*2.

IF(PMZ.GE.FSE)GO TO 1043

IF(PMZ.LT.FSE.AND.PMZ.GE.TTE)GO TO 1044

IF(PMZ.LT.TTE.AND.PMZ.GE.FMO)GO TO 1045

IF(PMZ.LT.FMO.AND.PMZ.GE.OTE)GO TO 1046

IF(PMZ.LT.OTE.AND.PMZ.GE.OSE)GO TO 1047

IF(PMZ.LT.OSE.AND.PMZ.GE.O.)GO TO 1048

WRITE(6,1049)PMZ

1049 FORMAT(1X,'PMZ IS IN ERROR PMZ=',F10.6)

CALL EXIT

C AT LEAST ONE PROPELLANT TANK AVAILABLE

1043 IZI=1

GO TO 1050

C AT LEAST TWO PROPELLANT TANKS AVAILABLE

1044 IZI=2

GO TO 1050

C AT LEAST THREE PROPELLANT TANKS AVAILABLE

1045 IZI=3

GO TO 1050

C AT LEAST FOUR PROPELLANT TANKS AVAILABLE

1046 IZI=4

GO TO 1050

C AT LEAST FIVE PROPELLANT TANKS AVAILABLE

1047 IZI=5

GO TO 1050

C ALL SIX PROPELLANT TANKS AVAILABLE

1048 PZ(K)=PFZ(K,6)

GO TO 1065

1050 PZ(K)=0.

DO 1052 IZ=IZI,6

1052 PZ(K)=PZ(K)+PFZ(K,IZ)

```

      GO TO 1065
16  ICTR=0
      WRITE(6,54)
      WRITE(6,61)
      GO TO 6
21  IERR=1
      GO TO 31
1065 IF (IERR.EQ.1) GO TO 3
40  CONTINUE
      3 IF (HALFZ.EQ.2) GO TO 7
      HALFZ=2
      KI=NK+1
      J=0
      WSC=WSC+PM
      GO TO 2
-7  INK=0
66  ICTR=0
      IK=INK+1
      WRITE(6,72)
72  FORMAT(1H1,7X,'MANEUVER',10X,'TOTAL',17X,'BURN',20X,'DELTA',18X,
1' TOTAL',16X,'TOTAL',/,9X,'NUMBER',10X,'IMPULSE',16X,'TIME',22X,
2' V',19X,'DELTA V',13X,'BURN TIME',/,25X,'(N-SEC)',15X,'(SEC.)',
318X,'(M/SEC)',16X,'(M/SEC)',15X,'(SEC)',/)
      DO 18 K=IK,NK
      WRITE(6,74) K,STI(K),STIME(K),SDELV(K),STDEL(K),STIM(K)
74  FORMAT(10X,I3,8X,E12.4,8X,E16.6,8X,E17.4,8X,E14.4,8X,F10.0,/)
      ICTR=ICTR+2
      INK=K
      IF (ICTR.GE.54) GO TO 66
18  CONTINUE
C   OUTPUT K VARIABLES
      INK=0
1051 ICTR=0
      IK=INK+1
      WRITE(6,1053)
1053 FORMAT(1H1,4X,'MANEUVER',2X,'TIME',5X,'SYSTEM',4X,
1' LEVEL OF SYSTEM AVAILABILITY (NO. OF PROP. TANKS)',6X,
2' RELIABILITY OF ',/,6X,'NUMBER',3X,'(HRS)',4X,'RELIAB',
36X,'1',8X,'2',8X,'3',8X,'4',8X,'5',8X,'6',7X,'THRUST SYSTEM',
4/,8X,'K',6X,'TIMEZ',6X,'PZ',4X,'PFZ(K,1)',1X,'PFZ(K,2)',
51X,'PFZ(K,3)',1X,'PFZ(K,4)',1X,'PFZ(K,5)',1X,'PFZ(K,6)',4X,
6' RE1Z(K)',1X,'RE2Z(K)',/)
      DO 1054 K=IK,NK
      WRITE(6,1055) K,TIMEZ(K),PZ(K),(PFZ(K,KK),KK=1,6),RE1Z(K),
1RE2Z(K)
1055 FORMAT(7X,I3,3X,F9.1,7(1X,F8.6),2X,2(1X,F8.6)/)
      ICTR=ICTR+2
      INK=K
      IF (ICTR.GE.54) GO TO 1051
1054 CONTINUE
      INK=0
1056 ICTR=0
      IK=INK+1
      WRITE(6,1057)
1057 FORMAT(1H1,4X,'MANEUVER',3X,'NUMBER OF ',5X,'FILL',3X,
1' HI PRESS PROP TANK',4X,'PROP TANK',9X,'BLADDER',11X,

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2'PRESSURE',/,6X,'NUMBER',5X,'CYCLES',7X,'VALVES',4X,
3'TANK',3X,'WELD RING',3X,'VALVE SYSTEM',5X,'RELIABILITY',
48X,'TRANSDUCER',/,8X,'K',5X,'CYCL1Z CYCL2Z',4X,'RFVZ',5X,
5'RTZ',7X,'RPTZ',5X,'RSP1Z',4X,'RSP2Z',5X,'RB1Z',4X,'RB2Z',
65X,'RPD1Z',3X,'RPD2Z',/)
DO 1058 K=IK,NK
WRITE(6,1059)K,CYCL1Z(K),CYCL2Z(K),RFVZ(K),RTZ(K),RPTZ(K),
1RSP1Z(K),RSP2Z(K),RB1Z(K),RB2Z(K),RPD1Z(K),RPD2Z(K)
1059 FORMAT(7X,I3,3X,2(1X,I6),2F9.6,1X,F9.6,1X,2F9.6,
12F9.6,2F9.6,/)
ICTR=ICTR+2
INK=K
IF (ICTR.GE.54)GO TO 1056
1058 CONTINUE
INK=0
1060 ICTR=0
IK=INK+1
WRITE(6,1061)
1061 FORMAT(1H1,4X,'MANEUVER',7X,'FILTER',10X,'THRUSTER',9X,
1'THRUSTER',6X,'HALF-SYS',2X,'WELD CONNECTION RELIAB',/,
26X,'NUMBER',7X,'ASSEMBLY',7X,'VALVE SYSTEM',6X,
3'RELIABILITY',4X,'CON. VALV',2X,'HP SYS',2X,'PRO SYS',1X,
4'THR SYS',/,8X,'K',8X,'RF1Z',4X,'RF2Z',5X,'RST1Z',4X,
5'RST2Z',4X,'RTH1Z',4X,'RTH2Z',5X,'BZ',6X,'RLHPZ',4X,
6'RLPPZ',4X,'RLTZ',/)
DO 1062 K=IK,NK
WRITE(6,1063)K,RF1Z(K),RF2Z(K),RST1Z(K),RST2Z(K),RTH1Z(K),
1RTH2Z(K),BZ(K),RLHPZ(K),RLPPZ(K),RLTZ(K)
1063 FORMAT(7X,I3,3X,2F9.6,2F9.6,2F9.6,F9.6,
13F9.6,/)
ICTR=ICTR+2
INK=K
IF (ICTR.GE.54)GO TO 1060
1062 CONTINUE
CALL EXIT
100 WRITE(6,63)
63 FORMAT(' READ IN ERROR')
CALL EXIT
114 WRITE(6,68)C3,C1,PG
68 FORMAT(' FM IS LE 0., C3 = 'E16.6,' C1 = ',E16.6,' PG = ',E16.6)
CALL EXIT
54 FORMAT(1H1,25X)
END

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0001      SUBROUTINE STINT (ARG1,ARG2,ARG3,PCT,KEY,NGRIPE,MINTBL,MAXTBL) 01 C0010
0002      DATA K002FX/5 / 01 00020
0003      DATA K001FX/6 / 01 C0030
0004      DIMENSIONNUMPTS(38),L1(37),L2(37),L3(37),STG(1765),DUMMY(10) 01 00040
0005      DIMENSION NAME (9) 01 00050
C      DIMENSIONNUMPTS(38),L1(37),L2(37),L3(37),STG(1765),DUMMY(10) 01 00060
C      DIMENSION NAME (9) 01 C0070
0006      EQUIVALENCE (NAT,L3(1)) 01 00080
C**** SIZE OF STG IS CALCULATED BY SUM OF ((1+N(ARG1))*(1+N(ARG2))) 01 00090
      NGRIPE=0 01 00100
      IF(KEY) 1,1,70 01 00110
      1 NG=1 01 C0120
      NORMAL=1 01 00130
      WRITE (K001FX,1357) 01 C0140
0012      1357 FORMAT (34H0 TABLE DATE CONTENTS) 01 00150
0013      GO TO 55 01 C0160
0014      2000 NG=2 01 00170
0015      NORMAL=2 01 00180
0016      3000 RETURN
0017      775 NGRIPE=1
0018      RETURN 01 C0230
0019      776 NGRIPE=2 01 00240
0020      WRITE (K001FX,9000) ARG1,ARG2,ARG3,MINTBL,MAXTBL 01 00250
0021      RETURN 01 C0260
0022      9000 FORMAT (20H0 ERROR IN ILU,ARG1=F12.5,6H ARG2=F12.5,6H ARG3=F12.5, 01 00270
      18H MINTBL=I4,8H MAXTBL=I4) 01 C0280
C      GRUMMEN AIRCRAFT ROUTINE FOLLOWS 01 00290
C      BEGINNING OF STINT 01 00300
      55 NUMTBL=1 01 00310
      NUMPTS(1)=0 01 C0320
0024      102 READ (K002FX,57) DA1,LA2,DA3,K,L1(NUMTBL),L2(NUMTBL),NAME,ISEQ 01 00330
0025      57 FORMAT (A2,A3,A3,I4,2I2,9A4,18X,I2) 01 C0340
0026      WRITE (K001FX,1157) K,DA1,LA2,DA3,NAME 01 C0350
0027      1157 FORMAT (I8,5X,A2,A3,A3,5X,9A4) 01 C0360
0028      104 IF (ISEQ) 69,58,69 01 C0370
0029      59 IF (K) 99,99,1159 01 C0380
0030      1159 IF (K-37) 59, 59,1103 01 C0390
0031      59 L9=L1(NUMTBL) 01 00400
0032      N1=(L8-1)/9+1 01 C0410
0033      DO 68 IS=1,N1 01 00420
0034      NAT=(IS-1)*9+1 01 C0430
0035      IF (IS-N1) 60,61,60 01 00440
0036      60 L4=NAT+8 01 C0450
0037      GO TO 62 01 C0460
0038      61 L4=L8 01 00470
0039      62 L5=NUMPTS(NUMTBL)+1 01 C0480
0040      L6=L5+NAT 01 00490
0041      L7=L5+L4 01 C0500
0042      JJ=0 01 00510
0043      L9=L2(NUMTBL) 01 00520
0044      LM=L5+L8 01 C0530
0045      LN=LM+L9 01 00540
0046      105 READ (K002FX,64) (DUMMY(K),K=1,10),ISEQ 01
0047      WRITE(K001FX,44) (DUMMY(K),K=1,10),ISEQ
0048      44 FORMAT (10E12.4,3X,I2)
0049      64 FORMAT (10E7.0,I2) 01 00560
0050

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0051	107	STG(L5)=DUMMY(1)	01	00570
0052		K=2	01	00580
0053		DO 65 J=L6,L7	01	00590
0054		STG(J)=DUMMY(K)	01	00600
0055	65	K=K+1	01	00610
0056		IF (ISEQ-((IS-1)*(L9+1)+JJ+1)) 69,66,69	01	00620
0057	66	L6=LN+NAT	01	00630
0058		L7=L6+L4	01	00640
0059		L5=L6+1+JJ	01	00650
0060		IF (JJ-L9) 67,68,69	01	00660
0061	67	JJ=JJ+1	01	00670
0062		LN=LN+L8	01	00680
0063		GO TO 105	01	00690
0064	68	CONTINUE	01	00700
0065	109	LEE=NUMPTS(NUMTBL)+(L8+1)*(L9+1)	01	00710
0066		IF (LEE-1765) 1100,1100,1101	01	00720
0067	1100	IF (NUMTBL-37) 1102,108,1103	01	00730
0068	1102	NUMPTS(NUMTBL+1)=LEE	01	00740
0069	108	NUMTEL=NUMTBL+1	01	00750
0070		GO TO 102	01	00760
0071	1101	WRITE (K001FX,1111) LEE	01	00770
0072		GO TO 775	01	00780
0073	1103	WRITE (K001FX,1113) NUMTBL	01	00790
0074		GO TO 775	01	00800
0075	1111	FORMAT (17H TOO MANY POINTS I8)	01	00810
0076	1113	FORMAT (17H TOO MANY TABLES I8)	01	00820
0077	69	GO TO (775,776,776),NG	01	00830
0078	70	IF (MINTBL-MAXTBL) 71,100,69	01	00840
0079	71	DO 73 NAT=MINTBL,MAXTEL	01	00850
0080		L4=NUMPTS(NAT)+1	01	00860
0081		IF (ARG3-STG(L4)) 72,74,73	01	00870
0082	72	IF (NAT-MINTBL) 69,69,75	01	00880
0083	73	CONTINUE	01	00890
0084		GO TO 69	01	00900
0085	75	L5=1	01	00910
0086		L6=2	01	00920
0087		L7=L4	01	00930
0088	101	DO 97 L8=L5,L6	01	00940
0089		L4=NUMPTS(NAT)+1	01	00950
0090		L9=L1(NAT)	01	00960
0091		LN=L9+L4	01	00970
0092		DO 77 LN=1,L9	01	00980
0093		JJ=L4+LN	01	00990
0094	2626	IF (ARG1-STG(JJ)) 76,78,77	01	01000
0095	76	IF (LN-1) 69,69,79	01	01010
0096	77	CONTINUE	01	01020
0097		GO TO 69	01	01030
0098	78	N1=-1	01	01040
0099		GO TO 80	01	01050
0100	79	N1=+1	01	01060
0101	80	K=L2(NAT)	01	01070
0102		DO 82 I=1,K	01	01080
0103		IDATE=LN+I	01	01090
0104		IF (ARG2-STG(IDATE)) 81,83,82	01	01100
0105	81	IF (I-1) 69,69,84	01	01110
0106	82	CONTINUE	01	01120

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0107	GO TO 69	01 C1130
0108	83 IS=-1	01 01140
0109	GO TO 85	01 01150
0110	84 IS=+1	01 01160
0111	85 ISEQ=LN+L2(NAT)+LN+(I-1)*L9	01 01170
0112	J=ISEQ-L9	01 01180
0113	K8=LN+(I-1)	01 01190
0114	K9=L4+LN-1	01 01200
0115	IF (N1+IS) 86,88,91	01 01210
0116	86 IF (STG(ISEQ)-999.E20) 87,69,69	01 01220
0117	87 PCT=STG(ISEQ)	01 01230
0118	GO TO 95	01 01240
0119	88 IF (N1) 89,69,93	01 01250
0120	89 IF (AMAX1(STG(ISEQ),STG(J))-999.E20) 90,69,69	01 01260
0121	90 PCT=STG(ISEQ)-(STG(IDATE)-ARG2)*(STG(ISEQ)-STG(J))/(STG(IDATE)-STG(K8))	01 01270
0122	GO TO 95	01 01280
0123	91 IF (AMAX1(STG(ISEQ),STG(J),STG(ISEQ-1),STG(J-1))-999.E20) 92,169,69	01 01290
0124	92 PCT=((STG(IDATE)-ARG2)*((STG(JJ)-ARG1)*STG(J-1)-(STG(K9)-ARG1)*STG(J))-(STG(K8)-ARG2)*((STG(JJ)-ARG1)*STG(ISEQ-1)-(STG(K9)-2ARG1)*STG(ISEQ)))/((STG(IDATE)-STG(K8))*(STG(JJ)-STG(K9))))	01 01300
0125	GO TO 95	01 01310
0126	93 IF (AMAX1(STG(ISEQ),STG(ISEQ-1))-999.E20) 94,69,69	01 01320
0127	94 PCT=STG(ISEQ)-(STG(JJ)-ARG1)*(STG(ISEQ)-STG(ISEQ-1))/(STG(JJ)-STG(K9))	01 01330
0128	95 GO TO (96,98,99),L8	01 01340
0129	96 DUMMY(1)=PCT	01 01350
0130	97 NAT=NAT-1	01 01360
0131	98 PCT=DUMMY(1)-(STG(L7)-ARG3)*(DUMMY(1)-PCT)/(STG(L7)-STG(L4))	01 01370
0132	99 GO TO (2000,3000),NORMAL	01 01380
0133	100 NAT=MINTBL	01 01390
0134	74 L5=3	01 01400
0135	L6=3	01 01410
0136	GO TO 101	01 01420
0137	C END STINT TABLE LOOK-UP	01 01430
	END	01 01440
		01 01450
		01 01460
		01 01470
		01 01480
		01 01490

APPENDIX B: Printout of Input Data and Computed Results

INPUT DATA
 TABLE 1
 DATE 01-03-71
 DPT VS PG FOR METAL DIAPHRAN
 0.0 0.9000Z 00 0.9100Z 00 0.9200Z 00 0.9300Z 00 0.9400Z 00 0.9500Z 00 0.9600Z 00 0.9700Z 00 0.9800Z 00 0.9900Z 00 1.0000Z 00 1.0100Z 00 1.0200Z 00 1.0300Z 00 1.0400Z 00 1.0500Z 00 1.0600Z 00 1.0700Z 00 1.0800Z 00 1.0900Z 00 1.1000Z 00 1.1100Z 00 1.1200Z 00 1.1300Z 00 1.1400Z 00 1.1500Z 00 1.1600Z 00 1.1700Z 00 1.1800Z 00 1.1900Z 00 1.2000Z 00 1.2100Z 00 1.2200Z 00 1.2300Z 00 1.2400Z 00 1.2500Z 00 1.2600Z 00 1.2700Z 00 1.2800Z 00 1.2900Z 00 1.3000Z 00 1.3100Z 00 1.3200Z 00 1.3300Z 00 1.3400Z 00 1.3500Z 00 1.3600Z 00 1.3700Z 00 1.3800Z 00 1.3900Z 00 1.4000Z 00 1.4100Z 00 1.4200Z 00 1.4300Z 00 1.4400Z 00 1.4500Z 00 1.4600Z 00 1.4700Z 00 1.4800Z 00 1.4900Z 00 1.5000Z 00 1.5100Z 00 1.5200Z 00 1.5300Z 00 1.5400Z 00 1.5500Z 00 1.5600Z 00 1.5700Z 00 1.5800Z 00 1.5900Z 00 1.6000Z 00 1.6100Z 00 1.6200Z 00 1.6300Z 00 1.6400Z 00 1.6500Z 00 1.6600Z 00 1.6700Z 00 1.6800Z 00 1.6900Z 00 1.7000Z 00 1.7100Z 00 1.7200Z 00 1.7300Z 00 1.7400Z 00 1.7500Z 00 1.7600Z 00 1.7700Z 00 1.7800Z 00 1.7900Z 00 1.8000Z 00 1.8100Z 00 1.8200Z 00 1.8300Z 00 1.8400Z 00 1.8500Z 00 1.8600Z 00 1.8700Z 00 1.8800Z 00 1.8900Z 00 1.9000Z 00 1.9100Z 00 1.9200Z 00 1.9300Z 00 1.9400Z 00 1.9500Z 00 1.9600Z 00 1.9700Z 00 1.9800Z 00 1.9900Z 00 2.0000Z 00 2.0100Z 00 2.0200Z 00 2.0300Z 00 2.0400Z 00 2.0500Z 00 2.0600Z 00 2.0700Z 00 2.0800Z 00 2.0900Z 00 2.1000Z 00 2.1100Z 00 2.1200Z 00 2.1300Z 00 2.1400Z 00 2.1500Z 00 2.1600Z 00 2.1700Z 00 2.1800Z 00 2.1900Z 00 2.2000Z 00 2.2100Z 00 2.2200Z 00 2.2300Z 00 2.2400Z 00 2.2500Z 00 2.2600Z 00 2.2700Z 00 2.2800Z 00 2.2900Z 00 2.3000Z 00 2.3100Z 00 2.3200Z 00 2.3300Z 00 2.3400Z 00 2.3500Z 00 2.3600Z 00 2.3700Z 00 2.3800Z 00 2.3900Z 00 2.4000Z 00 2.4100Z 00 2.4200Z 00 2.4300Z 00 2.4400Z 00 2.4500Z 00 2.4600Z 00 2.4700Z 00 2.4800Z 00 2.4900Z 00 2.5000Z 00 2.5100Z 00 2.5200Z 00 2.5300Z 00 2.5400Z 00 2.5500Z 00 2.5600Z 00 2.5700Z 00 2.5800Z 00 2.5900Z 00 2.6000Z 00 2.6100Z 00 2.6200Z 00 2.6300Z 00 2.6400Z 00 2.6500Z 00 2.6600Z 00 2.6700Z 00 2.6800Z 00 2.6900Z 00 2.7000Z 00 2.7100Z 00 2.7200Z 00 2.7300Z 00 2.7400Z 00 2.7500Z 00 2.7600Z 00 2.7700Z 00 2.7800Z 00 2.7900Z 00 2.8000Z 00 2.8100Z 00 2.8200Z 00 2.8300Z 00 2.8400Z 00 2.8500Z 00 2.8600Z 00 2.8700Z 00 2.8800Z 00 2.8900Z 00 2.9000Z 00 2.9100Z 00 2.9200Z 00 2.9300Z 00 2.9400Z 00 2.9500Z 00 2.9600Z 00 2.9700Z 00 2.9800Z 00 2.9900Z 00 3.0000Z 00 3.0100Z 00 3.0200Z 00 3.0300Z 00 3.0400Z 00 3.0500Z 00 3.0600Z 00 3.0700Z 00 3.0800Z 00 3.0900Z 00 3.1000Z 00 3.1100Z 00 3.1200Z 00 3.1300Z 00 3.1400Z 00 3.1500Z 00 3.1600Z 00 3.1700Z 00 3.1800Z 00 3.1900Z 00 3.2000Z 00 3.2100Z 00 3.2200Z 00 3.2300Z 00 3.2400Z 00 3.2500Z 00 3.2600Z 00 3.2700Z 00 3.2800Z 00 3.2900Z 00 3.3000Z 00 3.3100Z 00 3.3200Z 00 3.3300Z 00 3.3400Z 00 3.3500Z 00 3.3600Z 00 3.3700Z 00 3.3800Z 00 3.3900Z 00 3.4000Z 00 3.4100Z 00 3.4200Z 00 3.4300Z 00 3.4400Z 00 3.4500Z 00 3.4600Z 00 3.4700Z 00 3.4800Z 00 3.4900Z 00 3.5000Z 00 3.5100Z 00 3.5200Z 00 3.5300Z 00 3.5400Z 00 3.5500Z 00 3.5600Z 00 3.5700Z 00 3.5800Z 00 3.5900Z 00 3.6000Z 00 3.6100Z 00 3.6200Z 00 3.6300Z 00 3.6400Z 00 3.6500Z 00 3.6600Z 00 3.6700Z 00 3.6800Z 00 3.6900Z 00 3.7000Z 00 3.7100Z 00 3.7200Z 00 3.7300Z 00 3.7400Z 00 3.7500Z 00 3.7600Z 00 3.7700Z 00 3.7800Z 00 3.7900Z 00 3.8000Z 00 3.8100Z 00 3.8200Z 00 3.8300Z 00 3.8400Z 00 3.8500Z 00 3.8600Z 00 3.8700Z 00 3.8800Z 00 3.8900Z 00 3.9000Z 00 3.9100Z 00 3.9200Z 00 3.9300Z 00 3.9400Z 00 3.9500Z 00 3.9600Z 00 3.9700Z 00 3.9800Z 00 3.9900Z 00 4.0000Z 00 4.0100Z 00 4.0200Z 00 4.0300Z 00 4.0400Z 00 4.0500Z 00 4.0600Z 00 4.0700Z 00 4.0800Z 00 4.0900Z 00 4.1000Z 00 4.1100Z 00 4.1200Z 00 4.1300Z 00 4.1400Z 00 4.1500Z 00 4.1600Z 00 4.1700Z 00 4.1800Z 00 4.1900Z 00 4.2000Z 00 4.2100Z 00 4.2200Z 00 4.2300Z 00 4.2400Z 00 4.2500Z 00 4.2600Z 00 4.2700Z 00 4.2800Z 00 4.2900Z 00 4.3000Z 00 4.3100Z 00 4.3200Z 00 4.3300Z 00 4.3400Z 00 4.3500Z 00 4.3600Z 00 4.3700Z 00 4.3800Z 00 4.3900Z 00 4.4000Z 00 4.4100Z 00 4.4200Z 00 4.4300Z 00 4.4400Z 00 4.4500Z 00 4.4600Z 00 4.4700Z 00 4.4800Z 00 4.4900Z 00 4.5000Z 00 4.5100Z 00 4.5200Z 00 4.5300Z 00 4.5400Z 00 4.550

LIST OF VARIABLES WITH CORRESPONDING UNITS

[illegible]

INITIAL CONDITIONS

ORIFICE AREA = 0.2004E-06 SQ MET

ORIFICE DIAMETER = 0.5053E-03 SQ MET

PRESSURE AT REPRESSURIZATION = 0.1242E 07 N/SQ MET

MANEUVER NUMBER	PROP LEPT (KG)	TANK PRES (N/SQ M)	CHAM PRES (N/SQ M)	THRUST (N)	VEJ (M/SEC)	ISP (SEC)	FLOW RATE (KG/SEC)
1	0.1157E 03	0.3585E 07	0.1727E 07	0.1675E 02	0.22522E 04	229.81	0.7439E-02

(PRIOR TO START OF MANEUVER NO. 1)

MANEUVER NUMBER	PROP LEFT (KG)	TANK PRES (N/SQ M)	CHAM PRES (N/SQ M)	THRUST (N)	VEJ (M/SEC)	ISP (SEC)	FLOW RATE (KG/SEC)
1	0.1141E 03	0.3339E 07	0.1662E 07	0.1590E 02	0.22510E 04	229.69	0.7062E-02
2	0.1121E 03	0.3095E 07	0.1575E 07	0.1509E 02	0.22465E 04	229.23	0.6719E-02
3	0.1100E 03	0.2865E 07	0.1489E 07	0.1430E 02	0.22384E 04	228.41	0.6386E-02
4	0.9275E 02	0.1772E 07	0.1055E 07	0.9924E 01	0.21722E 04	221.65	0.4569E-02
5	0.9086E 02	0.1700E 07	0.1025E 07	0.9584E 01	0.21651E 04	220.93	0.4427E-02
6	0.8849E 02	0.1618E 07	0.9904E 06	0.9191E 01	0.21572E 04	220.12	0.4261E-02
7	0.8652E 02	0.1555E 07	0.9634E 06	0.8889E 01	0.21514E 04	219.53	0.4132E-02
8	0.8443E 02	0.1493E 07	0.9362E 06	0.8589E 01	0.21456E 04	218.94	0.4003E-02
9	0.6427E 02	0.1078E 07	0.7343E 06	0.6456E 01	0.20934E 04	213.61	0.3084E-02
10	0.6224E 02	0.1048E 07	0.7186E 06	0.6297E 01	0.20889E 04	213.15	0.3014E-02
11	0.6060E 02	0.1025E 07	0.7063E 06	0.6173E 01	0.20854E 04	212.79	0.2960E-02
12	0.5865E 02	0.9993E 06	0.6922E 06	0.6032E 01	0.20814E 04	212.39	0.2898E-02
13	0.5718E 02	0.9807E 06	0.6823E 06	0.5927E 01	0.20783E 04	212.07	0.2852E-02
14	0.3541E 02	0.7671E 06	0.5618E 06	0.4669E 01	0.20396E 04	208.13	0.2289E-02
15	0.3355E 02	0.7530E 06	0.5533E 06	0.4584E 01	0.20369E 04	207.85	0.2250E-02
16	0.3198E 02	0.7415E 06	0.5463E 06	0.4514E 01	0.20347E 04	207.62	0.2218E-02
17	0.3004E 02	0.7277E 06	0.5379E 06	0.4430E 01	0.20320E 04	207.34	0.2180E-02
18	0.2772E 02	0.7119E 06	0.5281E 06	0.4333E 01	0.20289E 04	207.02	0.2136E-02
19	0.8514E 01	0.6030E 06	0.4558E 06	0.3543E 01	0.20056E 04	204.65	0.1767E-02
20	0.6585E 01	0.5938E 06	0.4159E 06	0.3126E 01	0.19928E 04	203.35	0.1569E-02
21	0.6251E 01	0.5922E 06	0.3931E 06	0.2898E 01	0.19809E 04	202.13	0.1462E-02
22	0.1151E 03	0.3489E 07	0.1714E 07	0.1637E 02	0.22522E 04	229.81	0.7269E-02
23	0.9403E 02	0.1824E 07	0.1076E 07	0.1017E 02	0.21772E 04	222.16	0.4670E-02
24	0.9338E 02	0.1797E 07	0.1065E 07	0.1004E 02	0.21746E 04	221.90	0.4618E-02
25	0.7352E 02	0.1236E 07	0.8156E 06	0.7293E 01	0.21165E 04	215.97	0.3446E-02
26	0.7290E 02	0.1224E 07	0.8097E 06	0.7231E 01	0.21148E 04	215.80	0.3419E-02
27	0.7138E 02	0.1195E 07	0.7952E 06	0.7081E 01	0.21107E 04	215.38	0.3355E-02
28	0.7085E 02	0.1186E 07	0.7904E 06	0.7031E 01	0.21093E 04	215.24	0.3333E-02
29	0.6998E 02	0.1170E 07	0.7825E 06	0.6949E 01	0.21071E 04	215.01	0.3298E-02
30	0.6815E 02	0.1139E 07	0.7664E 06	0.6784E 01	0.21025E 04	214.54	0.3227E-02
31	0.6474E 02	0.1085E 07	0.7380E 06	0.6494E 01	0.20944E 04	213.72	0.3100E-02
32	0.3601E 02	0.7718E 06	0.5646E 06	0.4697E 01	0.20405E 04	208.22	0.2302E-02
33	0.2968E 02	0.7253E 06	0.5364E 06	0.4415E 01	0.20315E 04	207.29	0.2173E-02
34	0.2182E 02	0.6746E 06	0.5055E 06	0.4092E 01	0.20216E 04	206.28	0.2024E-02
35	0.1509E 02	0.6364E 06	0.4823E 06	0.3831E 01	0.20141E 04	205.52	0.1902E-02
36	0.8095E 01	0.6010E 06	0.4537E 06	0.3521E 01	0.20049E 04	204.59	0.1756E-02
37	0.6251E 01	0.5922E 06	0.3931E 06	0.2898E 01	0.19809E 04	202.13	0.1462E-02

HANDBOVER NUMBER	TOTAL IMPULSE (N-SEC)	BURN TIME (SEC.)	DELTA V (M/SEC)	TOTAL DELTA V (M/SEC)	TOTAL BURN TIME (SEC)
1	0.3808E 04	0.234000E 03	0.7006E 01	0.7006E 01	234.
2	0.8143E 04	0.280000E 03	0.7807E 01	0.1481E 02	514.
3	0.1288E 05	0.323000E 03	0.8633E 01	0.2344E 02	837.
4	0.5098E 05	0.323900E 04	0.7085E 02	0.9430E 02	4076.
5	0.5510E 05	0.422000E 03	0.7855E 01	0.1022E 03	4498.
6	0.6022E 05	0.546000E 03	0.9210E 01	0.1114E 03	5044.
7	0.6447E 05	0.470000E 03	0.7724E 01	0.1191E 03	5514.
8	0.6896E 05	0.516000E 03	0.8458E 01	0.1275E 03	6030.
9	0.1116E 06	0.580100E 04	0.8131E 02	0.2089E 03	11831.
10	0.1158E 06	0.666000E 03	0.7969E 01	0.2168E 03	12497.
11	0.1192E 06	0.553000E 03	0.6604E 01	0.2234E 03	13050.
12	0.1233E 06	0.668000E 03	0.7963E 01	0.2314E 03	13718.
13	0.1263E 06	0.510000E 03	0.6069E 01	0.2375E 03	14228.
14	0.1710E 06	0.859200E 04	0.8821E 02	0.3257E 03	22820.
15	0.1748E 06	0.824000E 03	0.8002E 01	0.3337E 03	23644.
16	0.1780E 06	0.703000E 03	0.6824E 01	0.3405E 03	24347.
17	0.1819E 06	0.889000E 03	0.7834E 01	0.3483E 03	25236.
18	0.1865E 06	0.107700E 04	0.8341E 01	0.3557E 03	26313.
19	0.2252E 06	0.988000E 04	0.7596E 02	0.4326E 03	36193.
20	0.2290E 06	0.113300E 04	0.7775E 01	0.4404E 03	37326.
21	0.2297E 06	0.222000E 03	0.1256E 01	0.4417E 03	37548.
22	0.1437E 04	0.870000E 02	0.2616E 01	0.2616E 01	87.
23	0.4819E 05	0.371100E 04	0.8563E 02	0.8824E 02	3798.
24	0.4961E 05	0.140000E 03	0.2615E 01	0.9086E 02	3938.
25	0.9217E 05	0.504500E 04	0.7866E 02	0.1695E 03	8983.
26	0.9347E 05	0.179000E 03	0.2528E 01	0.1720E 03	9162.
27	0.9669E 05	0.452000E 03	0.5480E 01	0.1775E 03	9614.
28	0.9780E 05	0.158000E 03	0.1908E 01	0.1794E 03	9772.
29	0.9962E 05	0.262000E 03	0.3160E 01	0.1826E 03	10034.
30	0.1035E 06	0.562000E 03	0.6768E 01	0.1894E 03	10596.
31	0.1106E 06	0.108400E 04	0.1347E 02	0.2028E 03	11680.
32	0.1699E 06	0.100000E 05	0.1161E 03	0.3189E 03	21680.
33	0.1826E 06	0.283900E 04	0.2645E 02	0.3454E 03	24519.
34	0.1985E 06	0.376100E 04	0.2906E 02	0.3744E 03	28280.
35	0.2120E 06	0.344400E 04	0.2650E 02	0.4009E 03	31724.
36	0.2260E 06	0.382900E 04	0.2934E 02	0.4303E 03	35553.
37	0.2297E 06	0.111600E 04	0.7203E 01	0.4375E 03	36669.

MANEUVER NUMBER K	TIME (HRS) TIMEZ	SYSTEM RELIAB PZ	LEVEL OF SYSTEM AVAILABILITY (NO. OF PROP. TANKS)						RELIABILITY OF THRUST SYSTEM	
			1 PFZ(K,1)	2 PFZ(K,2)	3 PFZ(K,3)	4 PFZ(K,4)	5 PFZ(K,5)	6 PFZ(K,6)	RE1Z(K)	RE2Z(K)
1	480.0	1.000000	0.000000	0.000000	0.000032	0.000004	0.002958	0.997006	1.000000	1.000000
2	504.0	1.000000	0.000000	0.000000	0.000033	0.000004	0.003106	0.996856	1.000000	1.000000
3	792.0	1.000000	0.000000	0.000000	0.000052	0.000010	0.004873	0.995065	1.000000	1.000000
4	816.0	1.000000	0.000000	0.000000	0.000054	0.000011	0.005020	0.994915	1.000000	1.000000
5	817.0	1.000000	0.000000	0.000000	0.000054	0.000011	0.005026	0.994909	1.000000	1.000000
6	1152.0	1.000000	0.000000	0.000000	0.000076	0.000021	0.007074	0.992828	1.000000	1.000000
7	1176.0	1.000000	0.000000	0.000000	0.000078	0.000022	0.007220	0.992680	1.000000	1.000000
8	1656.0	1.000000	0.000000	0.000001	0.000110	0.000043	0.010139	0.989707	1.000000	1.000000
9	1680.0	1.000000	0.000000	0.000001	0.000111	0.000045	0.010285	0.989559	1.000000	1.000000
10	1681.0	1.000000	0.000000	0.000001	0.000111	0.000045	0.010291	0.989552	1.000000	1.000000
11	2016.0	1.000000	0.000000	0.000001	0.000134	0.000064	0.012319	0.987482	1.000000	1.000000
12	2040.0	1.000000	0.000000	0.000001	0.000135	0.000066	0.012464	0.987334	1.000000	1.000000
13	2176.0	1.000000	0.000001	0.000001	0.000152	0.000089	0.014490	0.985262	1.000000	1.000000
14	2400.0	0.999998	0.000001	0.000001	0.000160	0.000091	0.014634	0.985114	1.000000	1.000000
15	2401.0	0.999999	0.000001	0.000001	0.000160	0.000091	0.014640	0.985109	1.000000	1.000000
16	2712.0	0.999998	0.000001	0.000002	0.000180	0.000115	0.016507	0.983195	1.000000	1.000000
17	2736.0	0.999998	0.000001	0.000002	0.000182	0.000118	0.016652	0.983047	1.000000	1.000000
18	3072.0	0.999998	0.000001	0.000002	0.000205	0.000148	0.018661	0.980984	1.000000	1.000000
19	3096.0	0.999998	0.000001	0.000002	0.000206	0.000150	0.018804	0.980837	1.000000	1.000000
20	3097.0	0.999998	0.000001	0.000002	0.000207	0.000150	0.018810	0.980831	1.000000	1.000000
21	3528.0	0.999997	0.000001	0.000003	0.000236	0.000195	0.021377	0.978190	1.000000	1.000000
22	3888.0	0.999622	0.000003	0.000004	0.000373	0.000236	0.023509	0.975877	1.000000	1.000000
23	4296.0	0.999591	0.000003	0.000005	0.000403	0.000287	0.025916	0.973388	1.000000	1.000000
24	4776.0	0.999555	0.000004	0.000006	0.000438	0.000354	0.028734	0.970466	1.000000	1.000000
25	5064.0	0.999135	0.000005	0.000007	0.000459	0.000398	0.030418	0.968717	1.000000	1.000000
26	5065.0	0.999135	0.000005	0.000007	0.000459	0.000398	0.030423	0.968712	1.000000	1.000000
27	5376.0	0.999061	0.000005	0.000008	0.000482	0.000448	0.032235	0.966826	1.000000	1.000000
28	5712.0	0.998978	0.000006	0.000009	0.000507	0.000505	0.034185	0.964793	1.000000	1.000000
29	6528.0	0.998763	0.000007	0.000011	0.000568	0.000657	0.038890	0.959873	1.000000	1.000000
30	6672.0	0.998723	0.000007	0.000012	0.000579	0.000685	0.039716	0.959007	1.000000	1.000000
31	6816.0	0.998682	0.000008	0.000012	0.000590	0.000715	0.040540	0.958142	1.000000	1.000000
32	7200.0	0.955839	0.000008	0.000014	0.000619	0.000796	0.042732	0.955839	1.000000	1.000000
33	7536.0	0.953826	0.000009	0.000015	0.000645	0.000871	0.044642	0.953826	1.000000	1.000000
34	7537.0	0.953821	0.000009	0.000015	0.000645	0.000871	0.044647	0.953821	1.000000	1.000000
35	7872.0	0.951819	0.000010	0.000016	0.000671	0.000948	0.046544	0.951819	0.999999	0.999999
36	7873.0	0.951814	0.000010	0.000016	0.000671	0.000949	0.046549	0.951814	0.999999	0.999999
37	8208.0	0.949815	0.000011	0.000018	0.000697	0.001029	0.048439	0.949815	0.999999	0.999999

PFZ(K,n) = probability of exactly n propellant tanks available and the remainder of the system functioning successfully.

RE1Z(K) = probability of thrust system of first half-system or second-half system or half-system valve functioning successfully.

RE2Z(K) = probability of thrust system of second half-system or first half-system and half-system valve functioning successfully.

MANEUVER NUMBER K	NUMBER OF CYCLES		FILL VALVES RFVZ	HI PRESS TANK RTZ	PROP TANK WELD RING RPTZ	PROP TANK VALVE SYSTEM		BLADDER RELIABILITY		PRESSURE TRANSDUCER	
	CYCL1Z	CYCL2Z				RSP1Z	RSP2Z	RB1Z	RB2Z	RPD1Z	RPD2Z
1	1	0	1.000000	0.999999	0.999999	1.000000	1.000000	0.999520	0.999520	0.999998	1.000000
2	2	0	1.000000	0.999999	0.999999	1.000000	1.000000	0.999496	0.999496	0.999995	1.000000
3	3	0	1.000000	0.999998	0.999998	1.000000	1.000000	0.999208	0.999208	0.999992	1.000000
4	4	0	1.000000	0.999998	0.999998	1.000000	1.000000	0.999184	0.999184	0.999960	1.000000
5	5	0	1.000000	0.999998	0.999998	1.000000	1.000000	0.999183	0.999183	0.999956	1.000000
6	6	C	1.000000	0.999997	0.999997	1.000000	1.000000	0.998849	0.998849	0.999951	1.000000
7	7	C	1.000000	0.999996	0.999996	1.000000	1.000000	0.998825	0.998825	0.999946	1.000000
8	8	0	1.000000	0.999995	0.999995	1.000000	1.000000	0.998345	0.998345	0.999941	1.000000
9	9	C	1.000000	0.999995	0.999995	1.000000	1.000000	0.998321	0.998321	0.999945	1.000000
10	10	C	1.000000	0.999995	0.999995	1.000000	1.000000	0.998320	0.998320	0.999979	1.000000
11	11	0	0.999999	0.999994	0.999994	1.000000	1.000000	0.997986	0.997986	0.999973	1.000000
12	12	0	0.999999	0.999994	0.999994	1.000000	1.000000	0.997962	0.997962	0.999867	1.000000
13	13	0	0.999999	0.999993	0.999993	1.000000	1.000000	0.997627	0.997627	0.999862	1.000000
14	14	0	0.999999	0.999993	0.999993	1.000000	1.000000	0.997603	0.997603	0.999778	1.000000
15	15	0	0.999999	0.999993	0.999993	1.000000	1.000000	0.997602	0.997602	0.999770	1.000000
16	16	0	0.999999	0.999992	0.999992	1.000000	1.000000	0.997292	0.997292	0.999763	1.000000
17	17	0	0.999999	0.999992	0.999992	1.000000	1.000000	0.997268	0.997268	0.999755	1.000000
18	18	0	0.999998	0.999991	0.999991	1.000000	1.000000	0.996933	0.996933	0.999744	1.000000
19	19	0	0.999998	0.999991	0.999991	1.000000	1.000000	0.996909	0.996909	0.999648	1.000000
20	20	0	0.999998	0.999991	0.999991	1.000000	1.000000	0.996908	0.996908	0.999637	1.000000
21	21	0	0.999998	0.999989	0.999989	0.999999	0.999999	0.996478	0.996478	0.999635	1.000000
22	21	1	0.999997	0.999988	0.999988	0.999999	0.999999	0.996119	0.996120	0.999635	0.999999
23	21	2	0.999997	0.999987	0.999987	0.999999	0.999999	0.995713	0.995713	0.999635	0.999963
24	21	3	0.999996	0.999986	0.999986	0.999999	0.999999	0.995235	0.995235	0.999635	0.999962
25	21	4	0.999995	0.999985	0.999985	0.999999	0.999999	0.994948	0.994949	0.999635	0.999913
26	21	5	0.999995	0.999985	0.999985	0.999999	0.999999	0.994947	0.994946	0.999635	0.999911
27	21	6	0.999995	0.999984	0.999984	0.999999	0.999999	0.994638	0.994638	0.999635	0.999907
28	21	7	0.999994	0.999983	0.999983	0.999998	0.999998	0.994304	0.994304	0.999635	0.999905
29	21	8	0.999992	0.999980	0.999980	0.999998	0.999998	0.993493	0.993493	0.999635	0.999902
30	21	9	0.999992	0.999980	0.999980	0.999998	0.999998	0.993350	0.993350	0.999635	0.999897
31	21	10	0.999992	0.999980	0.999980	0.999998	0.999998	0.993207	0.993207	0.999635	0.999886
32	21	12	0.999991	0.999978	0.999978	0.999997	0.999997	0.992826	0.992826	0.999635	0.999789
33	21	13	0.999990	0.999977	0.999977	0.999997	0.999997	0.992492	0.992492	0.999635	0.999762
34	21	14	0.999990	0.999977	0.999977	0.999997	0.999997	0.992491	0.992491	0.999635	0.999725
35	21	15	0.999989	0.999976	0.999976	0.999997	0.999997	0.992159	0.992159	0.999635	0.999692
36	21	16	0.999989	0.999976	0.999976	0.999997	0.999997	0.992158	0.992158	0.999635	0.999654
37	21	17	0.999988	0.999975	0.999975	0.999997	0.999997	0.991825	0.991826	0.999635	0.999644

MANEUVER NUMBER K	FILTER ASSEMBLY		THRUSTER VALVE SYSTEM		THRUSTER RELIABILITY		HALF-SYS CON. VALV	WELD CONNECTION		RELIAB
	RF1Z	RF2Z	RST1Z	RST2Z	RTH1Z	RTH2Z	BZ	HP SYS RLHPZ	PRO SYS RLPPZ	THR SYS RLTZ
1	0.999999	0.999999	1.000000	1.000000	0.999991	0.999991	1.000000	0.999986	0.999986	0.999986
2	0.999999	0.999999	1.000000	1.000000	0.999991	0.999991	1.000000	0.999985	0.999985	0.999985
3	0.999998	0.999998	1.000000	1.000000	0.999986	0.999986	1.000000	0.999976	0.999976	0.999976
4	0.999998	0.999998	1.000000	1.000000	0.999985	0.999985	1.000000	0.999976	0.999976	0.999976
5	0.999998	0.999998	1.000000	1.000000	0.999985	0.999985	1.000000	0.999976	0.999976	0.999976
6	0.999997	0.999997	1.000000	1.000000	0.999979	0.999979	1.000000	0.999965	0.999965	0.999965
7	0.999996	0.999996	1.000000	1.000000	0.999979	0.999979	1.000000	0.999965	0.999965	0.999965
8	0.999996	0.999995	1.000000	1.000000	0.999970	0.999970	1.000000	0.999950	0.999950	0.999950
9	0.999996	0.999995	1.000000	1.000000	0.999969	0.999970	1.000000	0.999950	0.999950	0.999950
10	0.999996	0.999995	1.000000	1.000000	0.999969	0.999970	1.000000	0.999950	0.999950	0.999950
11	0.999995	0.999994	1.000000	1.000000	0.999963	0.999964	1.000000	0.999940	0.999940	0.999940
12	0.999995	0.999994	1.000000	1.000000	0.999963	0.999963	1.000000	0.999939	0.999939	0.999939
13	0.999994	0.999993	1.000000	1.000000	0.999957	0.999957	1.000000	0.999929	0.999929	0.999929
14	0.999995	0.999993	1.000000	1.000000	0.999956	0.999957	1.000000	0.999928	0.999928	0.999928
15	0.999995	0.999993	1.000000	1.000000	0.999956	0.999957	1.000000	0.999928	0.999928	0.999928
16	0.999994	0.999992	1.000000	1.000000	0.999950	0.999951	1.000000	0.999919	0.999919	0.999919
17	0.999994	0.999992	1.000000	1.000000	0.999950	0.999951	1.000000	0.999918	0.999918	0.999918
18	0.999993	0.999991	1.000000	1.000000	0.999944	0.999945	1.000000	0.999908	0.999908	0.999908
19	0.999994	0.999991	1.000000	1.000000	0.999943	0.999944	1.000000	0.999907	0.999907	0.999907
20	0.999994	0.999991	1.000000	1.000000	0.999943	0.999944	1.000000	0.999907	0.999907	0.999907
21	0.999992	0.999989	0.999999	0.999999	0.999935	0.999937	0.999999	0.999894	0.999894	0.999894
22	0.999991	0.999988	0.999999	0.999999	0.999929	0.999930	0.999999	0.999883	0.999883	0.999883
23	0.999990	0.999987	0.999999	0.999999	0.999921	0.999923	0.999999	0.999871	0.999871	0.999871
24	0.999988	0.999985	0.999999	0.999999	0.999913	0.999914	0.999999	0.999857	0.999857	0.999857
25	0.999988	0.999984	0.999999	0.999999	0.999907	0.999909	0.999999	0.999848	0.999848	0.999848
26	0.999988	0.999984	0.999999	0.999999	0.999907	0.999909	0.999999	0.999848	0.999848	0.999848
27	0.999987	0.999983	0.999999	0.999999	0.999902	0.999903	0.999999	0.999839	0.999839	0.999839
28	0.999986	0.999982	0.999998	0.999998	0.999896	0.999897	0.999998	0.999829	0.999829	0.999829
29	0.999983	0.999980	0.999998	0.999998	0.999881	0.999882	0.999998	0.999804	0.999804	0.999804
30	0.999983	0.999979	0.999998	0.999998	0.999878	0.999879	0.999998	0.999800	0.999800	0.999800
31	0.999982	0.999979	0.999998	0.999998	0.999876	0.999877	0.999998	0.999796	0.999796	0.999796
32	0.999981	0.999977	0.999997	0.999997	0.999869	0.999870	0.999997	0.999784	0.999784	0.999784
33	0.999980	0.999975	0.999997	0.999997	0.999863	0.999863	0.999997	0.999774	0.999774	0.999774
34	0.999980	0.999975	0.999997	0.999997	0.999863	0.999863	0.999997	0.999774	0.999774	0.999774
35	0.999979	0.999974	0.999997	0.999997	0.999857	0.999857	0.999997	0.999764	0.999764	0.999764
36	0.999979	0.999973	0.999997	0.999997	0.999857	0.999857	0.999997	0.999764	0.999764	0.999764
37	0.999978	0.999972	0.999997	0.999997	0.999851	0.999851	0.999997	0.999754	0.999754	0.999754

APPENDIX C: Valve Configurations

One of the weakest links in auxiliary propulsion systems is the solenoid valve. Four commonly used valve redundancy configurations are: dual series, dual parallel, quad, and quad connected. These are illustrated below along with equations for their reliability. Two basic failure modes are considered; i.e., open failures and closed failures. Both an open and a closed failure will lead to a system failure in the absence of redundancy.

In general, let

R_o = probability of no open failure

R_c = probability of no closed failure

$Q_o = 1 - R_o$ = probability of open failure

$Q_c = 1 - R_c$ = probability of closed failure

$Q_s = Q_o + Q_c$ = probability of failure of a single valve

R = valve system reliability

Q = valve system unreliability

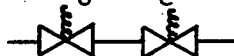
Single Valve



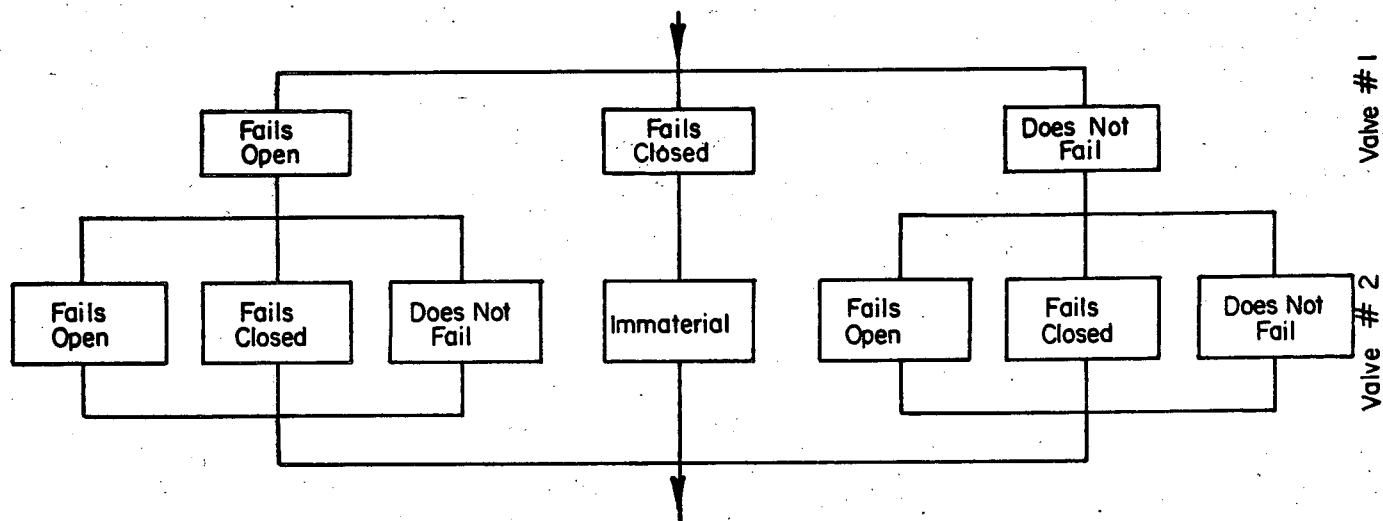
$$R = 1 - Q_s = 1 - Q_o - Q_c = 1 - (1 - R_o) - (1 - R_c)$$

$$R = R_o + R_c - 1$$

Dual Series



The various possible outcomes are shown below

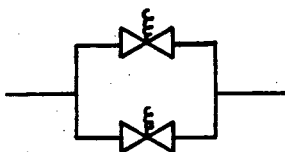


Therefore,

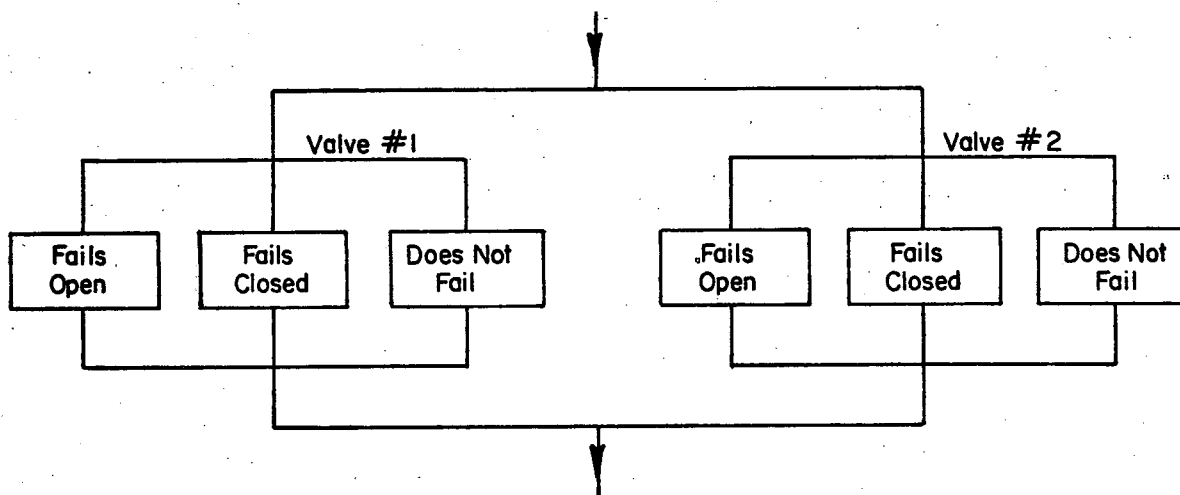
$$R = (1 - Q_o - Q_c)^2 + (1 - Q_o - Q_c) Q_o + Q_o (1 - Q_o - Q_c)$$

$$R = R_c^2 - (1 - R_o)^2$$

Dual Parallel



The various possible outcomes are shown below



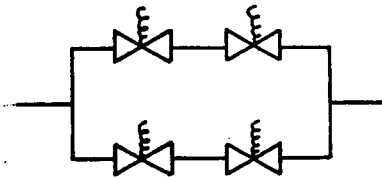
A system failure will occur if either valve fails in the open position or if both valves fail in the closed position. Therefore,

$$R = 1 - \left[1 - (1 - Q_o)^2 + Q_c^2 \right]$$

$$R = R_o^2 - (1 - R_c)^2$$

where $1 - (1 - Q_o)^2$ is the probability of an open failure and Q_c^2 is the probability of a closed failure.

Quad



The various possible outcomes can be structured in a manner similar to that shown above. It should be noted that the probability of a system failure is the sum of the probability of a failure due to an open valve arrangement and that due to a closed valve arrangement. Therefore,

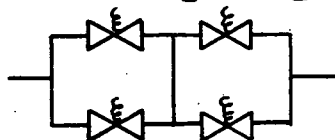
$$\text{probability of closed failure} = \left[1 - (1 - Q_c)^2 \right]^2$$

$$\text{probability of open failure} = 1 - (1 - Q_o^2)^2$$

$$R = 1 - \left[1 - (1 - Q_c)^2 \right]^2 - 1 + (1 - Q_o^2)^2$$

$$R = \left[1 - (1 - R_o)^2 \right]^2 - \left[1 - R_c^2 \right]^2$$

Quad Connected



In a manner similar to the Quad above,

$$\text{probability of closed failure} = 1 - \left[1 - Q_c^2 \right]^2$$

$$\text{probability of open failure} = \left[1 - (1 - Q_o)^2 \right]^2$$

$$R = 1 - \left[1 - (1 - Q_o)^2 \right]^2 - 1 + \left[1 - Q_c^2 \right]^2$$

$$R = \left[1 - (1 - R_c)^2 \right]^2 - \left[1 - R_o^2 \right]^2$$